## KNX manual

Flush-mounted blind/switch actuator JU 1, Flush-mounted blind actuator JU 1 RF


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## 1 N IMPORTANT WARNINGS!

## \. Risk of electric shock!

$>$ The device JU 1 RF does not have basic insulation around the terminals and plug connection!
> The inputs carry mains voltage!
$>$ When connecting the inputs or before any intervention at one of the inputs, interrupt the 230 V supply of the device.
> Protect against accidental contact during installation.
> Maintain a minimum distance of 3 mm from live parts or use additional insulation, e.g. separating strips/walls.
> Do not remove the insulation from the unused inputs.
> Do not cut off the conductors of the unused inputs.
$>$ Do not connect mains voltage ( 230 V ) or other external voltages to the inputs!
> During installation, ensure there is adequate insulation between mains voltage ( 230 V ) and bus or inputs (min. 5.5 mm ).

## 2 Function description

(1) The JU 1 device can be configured either as a 1-channel blind actuator (C1), or as a 2-channel switch actuator (C1, C2). ${ }^{1}$
The JU 1 RF device is a pure blind actuator.

Furthermore, both devices have 2 KNX binary inputs (I1, I2).

Usage as a blind actuator: JU 1, JU 1 RF

- 1-channel flush-mounted blind actuator.
- Configurable features: e.g. type of motor, response to power failure and restoration...
- 2 external inputs: can either be used for direct control of the actuator or as independent KNX binary inputs.
- Participation in central commands, such as up/down and save/call up scene.
- 8 individual positions can be preset and called up, for example via scenes.
- 5 safety objects: $3 x$ wind, rain and frost.
- Correction of improper drive connection via parameters.
- Start-up mode for electronic motors
- Teaching of runtime possible

Usage as a switch actuator: JU 1 only

- 2-channel flush-mounted switch actuator.
- Adjustable features: e.g. switching, delayed switching, pulse function.
- 2 external inputs: can either be used for direct control of the actuator or as independent KNX binary inputs.
- Links, type of contact (NC contact/NO contact) and participation in central commands such as permanent on, permanent off, central switching and save/call up scene.
- Switch functions: e.g. on/off, pulse, on/off delay, staircase light with forewarning.
- Logical links: e.g. block, AND, release, OR.
- Activation of the channel function via 1-bit telegram or 8-bit threshold.
- NTC input for actual temperature measurement.
- $\quad 4$-pole cable connection for external inputs.

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## 3 Operation

The device has 2 external inputs for buttons, switches, etc.
(1) In the initial delivery condition, i.e. prior to KNX programming, the actuator can be operated directly as a blind actuator with buttons at 11 and I 2 .

Depending on the setting of the 11 external input in the ETS, the actuator can be operated in 2 different ways:

Control via bus telegrams.
This is the classic configuration for a KNX actuator.
The actuator is controlled exclusively via bus telegrams.
(1) In this case, the external inputs I1 and 12 have no internal connection to the actuator.

Direct control (standard setting in the ETS) ${ }^{2}$
The actuator channels can be operated with conventional button ${ }^{3}$ or switch ${ }^{4}$.
These are connected directly to the external inputs I1 and I2.
(i) The input configured this way are then used exclusively for this function and are no longer connected to the bus, i.e. there are no communication objects.

The actuator itself retains all of its communication objects in this configuration.

See chapter "Application examples".
${ }^{2}$ Standard parameters button
${ }^{3}$ Blind and switch actuator
${ }^{4}$ Only switch actuator

## 4 Technical data

### 4.1 JU 1

| Operating voltage | KNX bus voltage |
| :---: | :---: |
| KNX bus current | 5 mA |
| Connection type | Screw terminals \| bus connection: KNX bus terminal |
| Type of installation | Flush-mounted |
| $L \times W \times D$ | $44.5 \times 44.5 \times 32$ |
| Max. cable cross-section | Solid: $0.5 \mathrm{~mm}^{2}(\emptyset 0.8)$ to $4 \mathrm{~mm}^{2}$ strand with crimp terminal: $0.5 \mathrm{~mm}^{2}$ to $2.5 \mathrm{~mm}^{2}$ |
| Number of channels | 1x blind or 2 x switching |
| Contact gap | < 3 mm ( $\mu$ contact) |
| Switch output | Floating, common connection in the middle. |
| Switching different phases | no |
| Type of contact | NO contact, 10 A per channel, max. 16 A per device |
| Resistive load | 2400 W |
| Incandescent/halogen lamp load | 800 W |
| Fluorescent lamp load (EB) | 58 W |
| Compact fluorescent lamps | 15 W |
| LED lamps | $\begin{aligned} & <2 \mathrm{~W}: 3 \mathrm{~W} \\ & >2 \mathrm{~W}: 30 \mathrm{~W} \end{aligned}$ |
| Suitable for SELV | Yes, if all channels switch SELV |
| Number of binary inputs | 2 |
| Ambient temperature | $-5^{\circ} \mathrm{C} \ldots+45^{\circ} \mathrm{C}$ |

(i) The switching capacity ratings for lamps with electronic ballast, such as LEDs, compact fluorescent lamps, fluorescent lamps with EB, etc., might vary depending on the technical characteristics of the ballasts.
(1)

The switching capacity ratings refer to a relay lifetime of at least 30000 switching cycles.
(1)

It is possible to exceed the switching capacity ratings for these lamps.
However, this will reduce the lifetime of the relay.

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### 4.2 JU 1 RF

| Operating voltage | KNX bus voltage |
| :---: | :---: |
| Standby output | < 0,4 W |
| Connection type | Screw terminals |
| Type of installation | Flush-mounted |
| $L \times W \times D$ | $44.5 \times 44.5 \times 32$ |
| Max. cable cross-section | Solid: $0.5 \mathrm{~mm}^{2}(\emptyset 0.8)$ to $4 \mathrm{~mm}^{2}$ <br> strand with crimp terminal: $0.5 \mathrm{~mm}^{2}$ to $2.5 \mathrm{~mm}^{2}$ |
| Number of channels | 1x blind |
| Contact gap | < 3 mm ( $\mu$ contact) |
| Switch output | Up, Down - non-floating |
| Switching different phases | no |
| Type of contact | NO contact, 5 A |
| Suitable for SELV | no |
| Number of binary inputs | 2 |
| Ambient temperature | $-5^{\circ} \mathrm{C} \ldots+45^{\circ} \mathrm{C}$ |
| Radio standard | KNX |
| Transmission frequency | 868,3 MHz |
| Transmission power | 10 mW |
| Coding | FSK (Frequency Shift Keying) |
| Transceiver type | Bidirectional |

Generally, it is not allowed to exceed the current and voltage ratings stated on the
device!

## 5 General information about KNX Secure

ETS5 Version 5.5 and higher support secure communication in KNX systems. A distinction is made between secure communication via the IP medium using KNX IP Secure and secure communication via the TP and RF media using KNX Data Secure. The following information refers to KNX Data Secure.

In the ETS catalogue, KNX products supporting "KNX-Secure" are clearly identified.

As soon as a "KNX-Secure" device is included in the project, the ETS requests a project password. If no password is entered, the device is included with Secure Mode deactivated. However, the password can also be entered or changed later in the project overview.

### 5.1 Start-up with "KNX Data Secure"

For secure communication, the FDSK (Factory Device Setup Key) is required. If a KNX product supporting "KNX Data Secure" is included in a line, the ETS requires the input of the FDSK. This device-specific key is printed on the device label and can either be entered by keyboard or read by using a code scanner or notebook camera.

Example of FDSK on device label:

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0048FF000000
Device Certificate (FDSK)
AABL57-P7KAAA-CAQDAQ-CQMBYI-BEFAWD-ANBYHT

4941670


After entering the FDSK, the ETS generates a device-specific tool key. The ETS sends the tool key to the device to be configured via the bus. The transmission is encrypted and authenticated with the original and previously entered FDSK key. Neither the tool key nor the FDSK key are sent in plain text via the bus.
After the previous action, the device only accepts the tool key for further communication with the ETS.
The FDSK key is no longer used for further communication, unless the device is reset to the factory setting: In this case, all set safety-related data will be deleted.
The ETS generates as many runtime keys as needed for the group communication you want to protect. The ETS sends the runtime keys to the device to be configured via the bus. Transmission takes place by encrypting and authenticating them via the tool key. The runtime keys are never sent in plain text via the bus.

The FDSK is saved in the project and can be viewed in the project overview.
Also, all keys of this project can be exported (backup).

During project planning, it can be defined subsequently which functions / objects are to communicate securely. All objects with encrypted communication are identified by the "Secure" icon in the ETS.

### 5.2 Start-up without "KNX Data Secure"

Alternatively, the device can also be put into operation without KNX Data Secure. In this case, the device is unsecured and behaves like any other KNX device without KNX Data Secure function.
To start up the device without KNX Data Secure, select the device in the 'Topology' or 'Devices' section and set the 'Secure start up' option in the 'Properties' area of the 'Settings' tab to 'Disabled'.

## 6 The JU 1 application programme

### 6.1 Selection in the product database

| Manufacturer | Theben AG |
| :--- | :--- |
| Product family | Output |
| Product type | JU 1, JU 1 RF |
| Programme name | $\mathrm{JU} 1, \mathrm{JU} 1 \mathrm{RF}$ |


| Number of communication objects | $48^{5}, 25^{6}$ |
| :--- | :--- |
| Number of group addresses | 254 |
| Number of associations | 255 |

(i) The ETS database can be found on our website: www.theben.de/en/downloads en

### 6.2 Overview of communication objects

### 6.2.1 Blind actuator

| No. | Object name | Function | Length | R | W | C | T | DPT |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| 1 | Channel C1 | UP / DOWN | 1 bit | - | W | C | - | 1,008 |
| 2 | Channel C1 | Step / stop | 1 bit | - | W | C | - | 1,007 |
| 3 | Channel C1 | \% height | 1 byte | - | W | C | - | 5,001 |
| 4 | Channel C1 | \% slat | 1 byte | - | W | C | - | 5,001 |
| 5 | Channel C1 | Block comfort/automatic | 1 bit | - | W | C | - | 1,001 |
| 6 | Channel C1 | 1 = block | 1 bit | - | W | C | - | 1,001 |
|  |  | 1 = enable | 1 bit | - | W | C | - | 1,003 |
| 7 | Channel C1 | Call up/save scenes | 1 byte | - | W | C | - | 18,001 |
| 8 | Channel C1 | Enable scenes = 1 | 1 bit | - | W | C | - | 1,003 |
|  |  | Block scenes = 1 | 1 bit | - | W | C | - | 1,001 |
| 9 | Channel C1 | Priority on safety | 2 bits | - | W | C | - | 2,001 |
| 10 | Channel C1 | Position A | 1 bit | - | W | C | - | 1,003 |
| 11 | Channel C1 | Position B | 1 bit | - | W | C | - | 1,003 |
| 12 | Channel C1 | Position C | 1 bit | - | W | C | - | 1,003 |
| 14 | Channel C1 | Presence | 1 bit | - | W | C | - | 1,001 |
| 15 | Channel C1 | Heating support | 1 bit | - | W | C | - | 1,001 |
| 16 | Channel C1 | Cooling support | 1 bit | - | W | C | - | 1,001 |
| 17 | Channel C1 | Room temperature | 2 bytes | - | W | C | - | 9,001 |
| 18 | Channel C1 | Height feedback 1 bit | 1 bit | R | - | C | T | 1,009 |
| 19 | Channel C1 | Height feedback \% | 1 byte | R | - | C | T | 5,001 |
| 20 | Channel C1 | Slat feedback \% | 1 byte | R | - | C | T | 5,001 |
| 21 | Channel C1 | Feedback comfort/automatic | 1 bit | R | - | C | T | 1,011 |
| 22 | Channel C1 | Start-up mode | 1 bit | - | W | C | - | 1,001 |
| 23 | Channel C1 | Send runtime | 2 bytes | R | - | C | T | 7,005 |
|  |  | Receive runtime | 2 bytes | - | W | C | - | 7,005 |
| 24 | Channel C1 | Window contact 1 | 1 bit | - | W | C | - | 1,001 |
| 25 | Channel C1 | Window contact 2 | 1 bit | - | W | C | - | 1,001 |
| 40 | Alarm | Excess temperature | 1 bit | R | - | C | T | 1,005 |

### 6.2.2 Switch actuator

| No. | Object name | Function | Length | R | W | C | T | DPT |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| 1 | Channel C1 | Switch object | 1 bit | - | W | C | - | 1,001 |
|  |  | Threshold 0.. 65535 | 2 bytes | - | W | C | - | 7,001 |
|  |  | Threshold EIS 5 (DPT 9.xxx) | 2 bytes | - | W | C | - | 9.xxx |
|  |  | Threshold as a percentage | 1 byte | - | W | C | - | 5,001 |
|  |  | Threshold 0.. 255 | 1 byte | - | W | C | - | 5,010 |
| 2 | Channel C1 | Switching with priority | 2 bits | - | W | C | - | 2,001 |
| 3 | Channel C1 | Logic input in XOR gate | 1 bit | - | W | C | - | 1,002 |
|  |  | Logic input in AND gate | 1 bit | - | W | C | - | 1,002 |
|  |  | Logic input in OR gate | 1 bit | - | W | C | - | 1,002 |
| 4 | Channel C1 | Block | 1 bit | - | W | C | - | 1,001 |
| 5 | Channel C1 | Call up/save scenes | 1 byte | - | W | C | - | 18,001 |
| 6 | Channel C1 | Block scenes = 1 | 1 bit | - | W | C | - | 1,001 |
|  |  | Enable scenes = 1 | 1 bit | - | W | C | - | 1,003 |
| 7 | Channel C1 | On/Off feedback | 1 bit | R | - | C | T | 1,001 |
| 8 | Channel C1 | Time to next service | 4 bytes | R | - | C | T | 13,100 |
|  |  | Operating hours feedback | 4 bytes | R | - | C | T | 13,100 |
| 9 | Channel C1 | Service required | 1 bit | R | - | C | T | 1,001 |
| 10 | Channel C1 | Reset operating hours | 1 bit | - | W | C | - | 1,001 |
|  |  | Reset service | 1 bit | - | W | C | - | 1,001 |
| 21-31: objects for channel C2 |  |  |  |  |  |  |  |  |
| 40 | Alarm | Excess temperature | 1 bit | R | - | C | T | 1,005 |

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### 6.2.3 External inputs: Switch/button function

| No. | Object name | Function | Length | R | W | C | T | DPT |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| 41 | Channel 11.1 | Switching | 1 bit | R | W | C | T | 1,001 |
|  |  | Priority | 2 bits | R | - | C | T | 2,001 |
|  |  | Send percentage value | 1 byte | R | - | C | T | 5,001 |
|  |  | Send value | 1 byte | R | - | C | T | 5,010 |
| 42 | Channel 17.2 | Switching | 1 bit | R | W | C | T | 1,001 |
|  |  | Priority | 2 bits | R | - | C | T | 2,001 |
|  |  | Send percentage value | 1 byte | R | - | C | T | 5,001 |
|  |  | Send value | 1 byte | R | - | C | T | 5,010 |
| 45 | Channel 11 | Block = 1 | 1 bit | - | W | C | - | 1,001 |
|  |  | Block = 0 | 1 bit | - | W | C | - | 1,003 |
| 51-55 | Channel I2 (details: see channel I1) |  |  |  |  |  |  |  |

### 6.2.4 External inputs: Dimming function

| No. | Object name | Function | Length | R | W | C | T | DPT |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| 41 | Channel 17 | Switching | 1 bit | R | W | C | T | 1,001 |
| 42 | Channel 11 | Brighter / darker | 4 bits | R | - | C | T | 3,007 |
|  |  | Brighter | 4 bits | R | - | C | T | 3,007 |
|  |  | Darker | 4 bits | R | - | C | T | 3,007 |
| 43 | Channel 11.1 | Switching | 1 bit | R | W | C | T | 1,001 |
|  |  | Priority | 2 bits | R | - | C | T | 2,001 |
|  |  | Send percentage value | 1 byte | R | - | C | T | 5,001 |
|  |  | Send value | 1 byte | R | - | C | T | 5,010 |
| 45 | Channel 11 | Block = 1 | 1 bit | - | W | C | - | 1,001 |
|  |  | Block = 0 | 1 bit | - | W | C | - | 1,003 |
| 51-55 | Channel I2 (details: see channel I1) |  |  |  |  |  |  |  |

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### 6.2.5 External inputs: Blinds function

| No. | Object name | Function | Length | R | W | C | T | DPT |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| 41 | Channel 11 | Step / stop | 1 bit | R | - | C | T | 1,010 |
| 42 | Channel 11 | UP / DOWN | 1 bit | R | W | C | T | 1,008 |
|  |  | UP | 1 bit | R | - | C | T | 1,008 |
|  |  | DOWN | 1 bit | R | - | C | T | 1,008 |
| 43 | Channel 11.1 | Switching | 1 bit | R | W | C | T | 1,001 |
|  |  | Priority | 2 bits | R | - | C | T | 2,001 |
|  |  | Send percentage value | 1 byte | R | - | C | T | 5,001 |
|  |  | Height \% ${ }^{7}$ | 1 byte | R | - | C | T | 5,001 |
|  |  | Send value | 1 byte | R | - | C | T | 5,010 |
|  |  | 2-byte 9.x | 2 bytes | R | - | C | T | 9.xxx |
|  |  | 4-byte 14.x | 4 bytes | R | - | C | T | 14.xxx |
| 44 | Channel 11.2 | Slat \% ${ }^{8}$ | 1 byte | R | - | C | T | 5,001 |
| 45 | Channel 11 | Block = 1 | 1 bit | - | W | C | - | 1,001 |
|  |  | Block $=0$ | 1 bit | - | W | C | - | 1,003 |
| 51-55 | Channel I2 (details: see channel I1) |  |  |  |  |  |  |  |

### 6.2.6 External inputs: Temperature input function (I2 only)

| No. | Object name | Function | Length | R | W | C | T | DPT |
| :---: | :--- | :--- | :--- | :--- | :--- | :--- | :--- | :--- |
| 51 | Channel 12 | Actual value for <br> temperature | 2 bytes | R | - | C | T | 9,001 |

### 6.2.7 External inputs: Window contact function

| No. | Object name | Function | Length | R | W | C | T | DPT |
| :---: | :--- | :--- | :--- | :--- | :--- | :---: | :---: | :---: |
| 41 | Channel I1 | Window contact 1 | 1 bit | R | - | C | T | 1,001 |
| 45 | Channel I1 | Block $=1$ | 1 bit | - | W | C | - | 1,001 |
|  |  | 1 bit | - | W | C | - | 1,003 |  |
| 41 | Channel I2 | Window contact 2 | 1 bit | R | - | C | T | 1,001 |
| 45 | Channel I2 | Block $=1$ | 1 bit | - | W | C | - | 1,001 |
|  |  | 1 bit | - | W | C | - | 1,003 |  |

[^1]
### 6.2.8 Common objects

### 6.2.8.1 Blind actuator

| No. | Object name | Function | Length | R | W | C | T | DPT |
| :--- | :--- | :--- | :--- | :--- | :--- | :--- | :--- | :--- |
| 74 | Central | Call up/save central scenes | 1 bytes | - | W | C | - | 18,001 |
| 75 | Central safety 1 | 1 | 1 bit | - | W | C | - | 1,002 |
| 76 | Central safety 2 | 2 | 1 bit | - | W | C | - | 1,002 |
| 77 | Central safety 3 | 3 | 1 bit | - | W | C | - | 1,002 |
| 78 | Central | UP / DOWN | 1 bit | - | W | C | - | 1,008 |
| 79 | Central safety | Rain | 1 bit | - | W | C | - | 1,002 |
| 80 | Central safety | Frost | 1 bit | - | W | C | - | 1,002 |

6.2.8.2 Switch actuator

| No. | Object name | Function | Length | R | W | C | T | DPT |
| :---: | :--- | :--- | :--- | :--- | :--- | :--- | :--- | :--- |
| 71 | Central | Central permanent ON | 1 bit | - | W | C | - | 1,001 |
| 72 | Central | Central permanent OFF | 1 bit | - | W | C | - | 1,001 |
| 73 | Central | Central switching | 1 bit | - | W | C | - | 1,001 |
| 74 | Central | Call up/save central scenes | 1 byte | - | W | C | - | 18,001 |

### 6.3 Description of communication objects

### 6.3.1 Objects for the blind actuator

Object 1: UP/DOWN
Raise the roller blinds/blinds with " 0 " and lower with " 1 ".

Object 2: Step/Stop
If the drive moves, it will be stopped when a Step/Stop telegram is received. If the drive is stationary at this moment, then a short slat turning (step) is performed on blinds. With the other drive types, the current position is adjusted up or down depending on the specified step direction.

The direction of the step is determined from whether a 0 or 1 is sent to the object.
No step is performed if the configured number of steps for a complete turn has already been reached.

## Object 3: \% Height

This raises/lowers the roller blinds/blinds to a certain height.
The setpoint value is expressed in \%.
$0 \% \ldots 3 \%$ = upper end position
$100 \%$ = lower end position
This function can be blocked by the comfort automatic object (see below).

Object 4: \% Slat
Specification of a particular slat turning in \%
This function can be blocked by the comfort automatic object (see below)

Object 5: Block Comfort/Automatic
A 1 on this object locks the functions Drive Height and Drive Slat.
This function is used to prevent the blind from being adjusted due to external influences, and to thus maintain a preferred slat position of the blinds.
The Up/Down function is maintained (object UP/DOWN).

## Object 6: Block/enable

Blocks the channel function.
Responses to the block being set and cancelled can be configured if the block function has been activated (Configuration options parameter page).

Object 7: Call up/save scenes
Only available if the scene function has been activated (Configuration options parameter page).
This object can be used to save and subsequently call up scenes.
Saving stores the channel status.
It does not matter how this status is produced (whether via switch commands, central objects or the buttons on the device). The saved status is restored when it is called up.
All scene numbers from 1 to 63 are supported.
Each channel can participate in up to 8 scenes.
The scene that is currently active can be ended with the value 63 (= scene 64).
See appendix: Scenes

Object 8: Block scenes / enable scenes
Blocks the scene function with a 1 or a 0 depending on the configuration.
As long as it is blocked, scenes cannot be saved or called up

Object 9: Priority on safety
Priority on safety will be used when the roller blinds or sun protection devices must remain stationary in an end position for a certain time, e.g. for window cleaning.

This operating mode has the highest priority level.
While priority on safety is active, all operating commands (UP/DOWN, \% Height, Step/Stop, Slat $\%)$, the other safety objects and the manual operation will be ignored.

| Object value | Priority on safety |
| :--- | :--- |
| 0 | inactive |
| 1 |  |
| 2 | DOWN |
| 3 |  |

Priority on safety is ended with a 1 or a 0.

## Object 10: Position A

With a 1, the drive is brought to the predefined position A (preset or end position).
See parameter page Positions via 1 bit.

## Object 11: Position B

With a 1, the drive is brought to the predefined position B (preset or end position).
See parameter page Positions via 1 bit.

## Object 12: Position C

With a 1 , the drive is brought to the predefined position C (preset or end position). See parameter page Positions via 1 bit.

Object 13
п.a.

Object 14: Presence
Presence status for the heating or cooling support.
See parameter page Sun protection.

Object 15: Heating support
Activate heating support, see parameter page Sun protection

Object 16: Cooling support
Activate cooling support, see parameter page Sun protection.

Object 17: Room temperature
Receives the current room temperature in ${ }^{\circ} \mathrm{C}$ for the sun protection function.

Object 18: Height feedback 1 bit
Current drive height feedback in as DPT1.009.

Object 19: Height feedback \%
Current drive height feedback in \%.

Object 20: Slat feedback \%
Current slat position feedback in \%.

Object 21: Feedback comfort/automatic
$0=$ Automatic operation: drive position is controlled e.g. by the weather station.
1 = Comfort active: The channel is currently in comfort mode, telegrams on the objects height \% and slat \% are not executed.

Object 22: Start-up mode
0 = Normal mode (no start-up)
1 = Activate start-up mode

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Object 23: Send runtime, receive runtime
The function of the object is dependent on the selected Drive runtime setting:

| Setting the drive runtime | Function | Usage |
| :--- | :--- | :--- |
| Teach in in start-up mode <br> (send) | Only in start-up mode: <br> Sends the runtime that is <br> determined for the channel to <br> all channels that are also in <br> start-up mode. | With the first DOWN command <br> after selection of the start-up <br> mode, the teaching-in of the <br> runtime begins by measuring <br> the time to the next Stop <br> command. <br> As soon as the Stop command <br> takes place, the measured <br> runtime will be saved, the <br> value sent and start-up <br> ended. |
| via object in start-up mode <br> (receive) | Only in start-up mode: <br> Receives the determined <br> runtime of the sending <br> channel | Runtime will be received, <br> saved, and start-up ended. |
| via ETS | not used. |  |

Object 24: Window contact 1
Input object for the first ${ }^{9}$ window contact of the ventilation function.

Object 25: Window contact 2
Input object for the second window contact of the ventilation function.
This is required to distinguish between window open and window tilted
(i)

The input objects channel C1 - window contact 1 and channel C1 - window contact 2 are not connected to inputs I 1 and I 2 internally. The connection is exclusively implemented via bus telegrams. ${ }^{10}$ For this purpose, these objects are connected with the objects channel 11 - window contact 1 and channel 12 - window contact 2 via group addresses.

[^2]
### 6.3.2 Objects for the switch actuator

Object 1: Switch object, threshold as a percentage, threshold 0..255, threshold DPT 9.xxx, threshold 0.. 65535
Input object: this object activates the set channel function (see parameter: Channel function).

The set channel function can either be activated via 1-bit telegram or by exceeding a threshold (8- or 16-bit telegram).

| Parameter |  | Activation of channel <br> function via |
| :--- | :--- | :--- |
| Activation of function <br> via | Type of threshold object | 1-bit telegram |
| Switch object |  | Exceeding per cent value |
| Exceeding the <br> threshold | Object type: Per cent (DPT 5.001) | Object type: Counter value 0..255 (DPT <br> $5.010)$ |
|  | Any value in given numerical <br> range |  |
|  |  |  |

Object 2: Switching with priority
Priority control:

| Status of object <br> Switching with priority | Channel status |
| :---: | :--- |
| 0 | As specified by the input object ${ }^{11}$ |
| 1 | OFF |
| 2 | ON |
| 3 |  |

Object 3: Logic input in AND gate, in OR gate, in XOR gate
Only available if link is activated (Configuration options parameter page).
Forms a logical link together with the input object to activate the channel function.

Object 4: Block
Blocks the channel function.
Responses to the block being set and cancelled can be configured if the block function has been activated (Configuration options parameter page).

[^3]Object 5: Call up/save scene
Only available if the scene function has been activated (Configuration options parameter page).
This object can be used to save and subsequently call up scenes.
Saving stores the channel status.
It does not matter how this status is produced (whether via switch commands, central objects or the buttons on the device).
The saved status is restored when it is called up.
All scene numbers from 1 to 64 are supported.
Each channel can participate in up to 8 scenes.
See appendix: Scenes

Object 6: Block scenes = 1, enable scenes = 1
Blocks the scene function with a 1 or a 0 depending on the configuration.
As long as it is blocked, scenes cannot be saved or called up.

Object 7: On/Off feedback
Reports the current channel status.
The status can also be inverted depending on configuration.

Object 8: Time to next service, operating hours feedback
Only available if the hour counter function is activated
(Configuration options parameter page).
Reports, depending on selected type of hour counter (Hour counter and service parameter page), either the remaining time to the next service or the current status of the hour counter.

Object 9: Service required
Only available if the hour counter function has been activated (Configuration options parameter page) and Type of hour counter $=$ Counter for time to next service.

Reports if the next service is due.
$0=$ not due
1 = service is due.

Object 10: Reset service, reset operating hours

| Function | Usage |
| :--- | :--- |
| Reset service ${ }^{12}$ | Reset service interval counter. |
| Reset operating hours ${ }^{13}$ | Reset hour counter |

${ }^{12}$ Depending on configuration
${ }^{13}$ Depending on configuration

### 6.3.3 Objects for the external inputs: Switch function

Object 41: Channel I1.1
First output object of the channel (first telegram).
4 telegram formats can be set:
Switching ON/OFF, priority, send percentage value, send value.

Object 42: Channel 11.2
Second output object of the channel (second telegram).
4 telegram formats can be set:
Switching ON/OFF, priority, send percentage value, send value.

Object 45: Channel 11 block $=1$, or block $=0$
The channel is blocked via this object.
The acting direction of the block object and behaviour when the block is set or cancelled can be configured.

Objects 51-55
Objects for channel I2

### 6.3.4 Objects for the external inputs: Button function

Object 41: Channel I1.1
First output object of the channel (first telegram).
4 telegram formats can be set:
Switching ON/OFF, priority, send percentage value, send value.

Object 42: Channel I1.2
Second output object of the channel (second telegram).
4 telegram formats can be set:
Switching ON/OFF, priority, send percentage value, send value.

Object 45: Channel 11 block $=1$, or block $=0$
The channel is blocked via this object.
The acting direction of the block object and behaviour when the block is set or cancelled can be configured.

Objects 51-55
Objects for channel I2

### 6.3.5 Objects for the external inputs: Dimming function

Object 41: Channel I1.1 switching
Switches the dimmer on and off.

Object 42: Channel 11.1 brighter, darker, brighter / darker
4-bit dimming commands.

Object 43: Channel 11.1 switching, priority, percentage..
Output object for the additional function with double-click.
4 telegram formats can be set:
Switching ON/OFF, priority, send percentage value, send value.

Object 45: Channel I1 block $=1$, or block $=0$
The channel is blocked via this object.
The acting direction of the block object and behaviour when the block is set or cancelled can be configured.

Objects 51-55
Objects for channel I2

### 6.3.6 Objects for the external inputs: Blinds function

Object 41: Channel I1 step / stop
Sends step/stop commands to the blind actuator.

Object 42: Channel I1 UP/DOWN, UP, DOWN
Sends operating commands to the blind actuator.

Object 43: Channel 11.1 switching, priority, percentage.., height \%
Output object for the additional function with double-click.
5 telegram formats can be set:
Switching ON/OFF, priority, send percentage value, send value, height \%.

Object 44: Channel 11.1 slat \%
Slat telegram for positioning the blinds upon double-click (together with object height $\%$, with object type $=$ height + slat).

Object 45: Channel 11 block $=1$, or block $=0$
The channel is blocked via this object.
The acting direction of the block object and behaviour when the block is set or cancelled can be configured.

Objects 51-55
Objects for channel I2

### 6.3.7 Objects for the external inputs: Temperature input function

Object 51: Channel 12 actual value for temperature ${ }^{14}$
Sends the temperature measured at input I2 (remote sensor or floor temperature sensor).

14 The temperature input function is only possible with input I2.

### 6.3.8 Objects for the external inputs: Window contact function

$$
\begin{aligned}
& \text { The output objects channel } 11 \text { - window contact } 1 \text { and channel } 12 \text { - window } \\
& \text { contact } 2 \text { are not connected to blind actuator channel C1 internally. } \\
& \text { The connection is exclusively implemented via bus telegrams. }{ }^{15} \\
& \text { For this purpose, these objects are connected with the objects } \\
& \text { channel C1 - window contact } 1,2 \text { of the actuator via group addresses. }
\end{aligned}
$$

Object 41: Channel 11 window contact 1
First output object of the channel (first telegram).
4 telegram formats can be set:
Switching ON/OFF, priority, send percentage value, send value.

Object 45: Channel 11 block $=1$, or block $=0$
The channel is blocked via this object.
The acting direction of the block object and behaviour when the block is set or cancelled can be configured.

Objects 51-55
Objects for channel I2
${ }^{15}$ In this way, window contact inputs I 1 and I 2 can be used for C 1 , as well as for other bus sharing units, blind actuators (displays etc.).

### 6.3.9 Common objects for the blind actuator

Object 40: Excess temperature
Reports when the device has reached too high a temperature, e.g. because the maximum current has been exceeded, and has switched the output off.

Object 74: Call up/save central scenes
Central object for using scenes.
This object can be used to save and subsequently call up scenes.
See appendix: Scenes

Objects 75, 76, 77: Central safety 1, 2, 3
The safety objects allow a specific response of the drives to a particular situation with a high priority. These objects can, for example, be linked with 3 differently placed wind sensors (weather stations).

Example: A safety object is linked to a wind sensor.
A drive to which a textile sun protection device is connected is configured to react to this safety object.
The operating condition is normal as long as a 0 is present. In the event of a storm, the wind sensor sends a 1 to the safety object and the sun protection is immediately moved to the configured safety position.

A safety object must only be actuated by one device, as otherwise conflicting commands could cancel each other out.

With a request for safety objects e.g. via the ETS function "Read value": If the Safety on status arises through cyclical monitoring, the object value remains at 0

$\triangle$The safety statuses must be reinitialized after download.

## Object 78: Central Up/Down

This object can be used to centrally control all drives which are configured for it.
For example, all of the roller blinds on one facade can be raised or lowered at the same time with one button
0 = raise
1 = lower

Object 79: Central safety rain
This object can be used to move all drives which are configured for it into a defined position when there is a central rain alarm.

Object 80: Central safety frost
This object can be used to move all drives which are configured for it into a defined position when there is a central frost alarm.

### 6.3.10 Common objects for the switch actuator

Object 40: Excess temperature
Reports when the device has reached too high a temperature, e.g. because the maximum current has been exceeded, and has switched the output off.

Object 71: Central permanent ON
Central switch-on function.
$0=$ no function
1 = permanent ON

Participation in this object can be configured
(Configuration options parameter page).
(1) This object takes top priority.

As long as it is set, other switch commands will not work on the participating channel.

Object 72: Central permanent OFF
Central switch-off function.
$0=$ no function
1 = permanent OFF
Participation in this object can be configured
(Configuration options parameter page).

(i)
This object has the second highest priority after Central permanent ON. As long as it is set, other switch commands will not work on the participating channel.

Object 73: Central switching
Central switch function.
$0=0 F F$
$1=0 \mathrm{~N}$
Participation in this object can be configured
(Configuration options parameter page).
With this object, the participating channel responds exactly as if its input object were receiving a switch command.

Object 74: Call up/save central scenes
Central object for using scenes.
This object can be used to save and subsequently call up "scenes".
See appendix: Scenes

### 6.4 Parameter pages overview

### 6.4.1 General

| Parameter page | Description |
| :--- | :--- |
| General | General parameters: Selection of switch actuator or blind actuator, etc. |

### 6.4.2 Blind actuator JU 1, JU 1 RF

| Parameter page | Description |
| :--- | :--- |
| Blind actuator channel C1 |  |
| Configuration options | Characteristics of channel and activation of additional functions <br> (scenes, sun protection, block, etc.). |
| Drive settings | Direction of movement, runtimes, etc. |
| Sun protection | Heating and cooling support settings. |
| Positions via 1 bit | Behaviour when calling up or leaving the 1-bit positions |
| Ventilation | Automatic positioning of blinds or roller blinds when opening the <br> window. |
| Safety wind / rain / <br> frost | Priority and participation in the safety objects for wind, rain and frost. |
| Presets | 8 preset heights and slat positions that can be called up via scenes or <br> 1-bit objects. |
| Restoration of power | Behaviour during failure and restoration of bus and mains power. |
| Block function | Type of block telegram and response to blocking. |
| Scenarios | Selection of scene numbers relevant to the channel. |

### 6.4.3 Switch actuator JU 1

| Parameter page | Description |
| :---: | :---: |
| Switch actuator channel C1/C2 |  |
| Configuration options | Characteristics of channel and activation of additional functions (scenes, links, etc.). |
| Contact characteristics | Type of contact and status after download, bus failure, etc. |
| Threshold | Settings for triggering channel function through exceeding threshold. |
| Block function | Type of block telegram and response to blocking. |
| Scenes | Selection of scene numbers relevant to the channel. |
| Feedback | Status of feedback object, etc. |
| Hour counter and service | Type of hour counter and, if applicable, service interval, etc. |
| Link | Selection of logical link. |

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### 6.4.4 External inputs

| Parameter page | Description |
| :--- | :--- |
| External inputs I1, I2 |  |
| Configuration options | Function of the input, debounce time, number of telegrams, block <br> function, etc. <br> Additionally in the case of I2: Selection of the temperature sensor, <br> temperature calibration, etc. |
| Switch object 1, 2 | Object type, transmission behaviour, etc. can be set for each object <br> individually. |
| Direct switching | Switching statuses in the case of direct control |
| Button object 1, 2 | Object type, transmission behaviour, etc. can be set for each object <br> individually. |
| Dimming | Type of control. |
| Blinds | Type of control. |
| Double-click | Additional telegrams for Dimming and Blinds. |
| Window contact | Direction of action, cycl. Transmission, etc. |

### 6.5 General parameters

### 6.5.1 General

> (1) The first parameter, Usage, defines the purpose of the device, and should be set first.

| Designation | Values | Description |
| :---: | :---: | :---: |
| Usage | 1-channel blind actuator | The device is used as a blind actuator. |
|  | 2-channel switch actuator | The device is used as a 2 -fold switch actuator. |
| Use external inputs | No <br> Yes | The actuator is exclusively controlled via the bus. <br> 2 binary inputs are available. <br> Possible functions: <br> 11: Control actuator directly (button/switch function) or KNX binary input. <br> 12: Control actuator directly (button/switch function) or KNX binary input with temperature. |
| Send excess temperature alarm ${ }^{16}$ cyclically | always cyclically <br> only send cyclically in case of an error | The alarm info object always sends the current status cyclically and in the event of a change: Only sends in case of an error, cyclically and in the event of a change. |
| Cycle time | every min every 2 min every 3 min every 30 min every 45 min every 60 min | Cycle time for the alarm info object |

${ }^{16}$ When the temperature in the device increases too much due to overloading,
the output is switched off and an alarm telegram is sent.
Normal operation cannot be resumed until the temperature has dropped by around 40 K.

### 6.6 Parameters for the blind actuator

### 6.6.1 Channel C1: Configuration options

| Designation | Values | Description |
| :---: | :---: | :---: |
| Type of hanging | Blinds <br> Roller blinds / awning / general drive... | The type of hanging which is to be actuated |
| Setting the drive runtime | via ETS <br> Teach in in start-up mode (send) <br> via object in start-up mode (receive) | Runtime is set on the parameter page Drive settings. <br> In start-up mode, this channel should send the taught-in runtime to the other channels. <br> In start-up mode, this channel should receive and apply the taught-in runtime from another channel. |
| Response after download | Maintain runtime <br> Delete runtime | Not available with Drive runtime setting = via ETS. <br> Download has no influence on the taught-in runtime <br> Taught-in runtime is deleted during download. |
| Activate sun protection | yes <br> no | Activate sun protection function with heating or cooling support. <br> No sun protection function. |
| Activate ventilation function | yes <br> no | When opening the window, the blinds or roller blinds move automatically to a defined position. <br> No ventilation function. |
| Activate block function | $\begin{aligned} & \hline \text { Yes.. } \\ & \text { no } \end{aligned}$ | Should the block function be used? |
| Activate scenes | Yes.. no | Should scenes be used? |
| Direction of drive run | normal <br> inverted | Standard setting: Hanging moves from top to bottom. <br> For special applications or quick fix for wrongly wired devices (up/down directions mixed up). |
| Block Comfort/Auto on UP/DOWN/STOP command |  | Suppression of the Comfort/Auto function with manual positioning via On, Off or Stop telegrams. |


| Designation | Values | Description |
| :---: | :---: | :---: |
|  | no, only via object Comfort/Automatic <br> yes, and via object Comfort/Automatic OFF <br> yes, and after 0.5 h OFF yes, and after 1 h OFF <br> yes, and after 2 h OFF <br> yes, and after 48 h OFF | No suppression: Comfort/Auto remains active after manual positioning. <br> Comfort/Auto can be ended both by manual positioning and via the object Comfort/Automatic <br> The Comfort/Auto function is blocked for the set time via manual positioning. Once this time has lapsed, Comfort/Auto is active once again and the drive reacts to height telegrams. <br> The block can be ended at any time via the object Comfort / Automatic (=0). |
| Response after return to automatic operation | No response Update height \% / slat \% | Response after the Block Comfort/Auto object has been reset to 0 . |

### 6.6.2 Drive settings

| Designation | Values | Description |
| :---: | :---: | :---: |
| Complete runtime Down | manual input <br> 5.. 500 | Only available when Drive runtime setting = via ETS. Enter the measured runtime for descending (in seconds). |
| Drive start-up time | $0 . .1000 \mathrm{~ms}$ | Time until the drive motor has reached its full output. <br> This time is usually determined empirically. |
| Runtime adjustment for ascent | $\begin{aligned} & \text { manual input } \\ & -15 . .+15 \end{aligned}$ | Enter difference between runtime when ascending and runtime (in seconds) when descending. <br> Correction value $=$ tup - toown |
| Step duration of Step/Stop object ${ }^{17}$ | ```no steps 250 ms 500 ms 1s 2s 3s 4s 5s 6s 7s 10s``` | Only for roller blinds/awning/general drive. This specifies whether or not it should be possible to adjust the drive in small steps, and it also specifies the duration of a single step. |
| Tighten fabric (awning) | yes <br> no | Only for roller blinds/awning/general drive. At values above $70 \%$, the hanging, awning or roller blinds will be retightened by moving back briefly. <br> On roller blinds it is guaranteed that the vent slots will remain open. <br> no tightening. |
| Complete slat turning 4 ... 250 | 4 .. 250 | Enter the measured turn time of the slats in increments of 100 ms . $10=10 \times 100 \mathrm{~ms}=1 \mathrm{~s}$ |
| No. of steps for a complete turn ${ }^{18}$ | 3 steps <br> 4 steps <br> 7 steps <br> ... <br> 12 steps | This specifies the number of individual steps a complete slat turn is to be divided into (3 to 12). |

[^4]| Designation | Values | Description |
| :--- | :--- | :--- |
| On receipt of a step/stop <br> command | process immediately <br> (recommended) <br> Wait 0.3 s to see if an <br> UP/DOWN command <br> follows <br> Wait 0.4 s to see if an <br> UP/DOWN command <br> follows <br> Wait 0.5 s to see if an <br> UP/DOWN command <br> follows | Every received step command is <br> carried out immediately. |
| Step commands are only <br> executed if no operating <br> command is received within the <br> set time. <br> These settings apply to push <br> buttons which, when pressed <br> and held, first send a step <br> command and then an operating <br> command. |  |  |
| Pause time before reversal of <br> direction | 0.5 s <br> 1 s <br> 2 s <br> 3 s | Pause introduced to protect the <br> drive motor against conflicting <br> commands (e.g. if a descend <br> command is received while <br> ascending). <br> This setting depends on the <br> information supplied by the <br> manufacturer of the drive |
| Automatic execution of the slat <br> object value <br> [\%] after the height object [\%] | yes <br> no | Selection whether or not the slat <br> position (according to the slat <br> object \%) is to be resumed after <br> the height adjustment via the <br> height object \%. |
| Assignment of the 0\% position <br> to the slat objects [\%] | 0\% corresponds to slat <br> position on lowering <br> 0\% corresponds to slat <br> position on ascending | Input of the starting position for <br> the calculation of the slat turn. |
| Participation in central Up/Down <br> object | yes <br> no | Should the drive respond to the <br> central object? |
| Transmission of feedback | only at change <br> cyclically and at change | When should feedback <br> (obj. slat feedback and height <br> feedback) be sent? |
| Time for cyclical transmission of <br> feedback | 2 minutes, 3 minutes, <br> 5 minutes, 10 minutes, <br> 15 minutes, 20 minutes, <br> 30 minutes, 45 minutes <br> 60 minutes | Ifyclically, at what interval? |

### 6.6.3 Sun protection

(i) As soon as a room is not occupied, the sun protection function can be used to save energy costs again and again.
For this purpose, the sunlight is deliberately let in during the winter, while protection is provided in summer by moving down the blinds or roller blinds, if required.

| Designation | Values | Description |
| :---: | :---: | :---: |
| Desired room temperature during sun protection mode | $\begin{aligned} & 15^{\circ} \mathrm{C}-30^{\circ} \mathrm{C} \\ & \text { Default }=21^{\circ} \mathrm{C} \end{aligned}$ | Setpoint for heating or cooling support (see below). |
| Response to presence in sun protection mode (presence object $=1$ ) | Preset 1, Preset 2 <br> Preset 3, Preset 4 <br> Preset 5, Preset 6 <br> Preset 7, Preset 8 <br> top end position <br> lower end position <br> no reaction, unchanged <br> update <br> (height / slat) | Approach a preset position. See Presets parameter page. <br> Approach an end position. <br> Do not respond. <br> Approach last received position. |
| Response to heating support | Preset 1, Preset 2 <br> Preset 3, Preset 4 <br> Preset 5, Preset 6 <br> Preset 7, Preset 8 <br> top end position <br> lower end position | If the conditions for heating support are fulfilled, i.e.: <br> - Heating support obj. = 1 <br> - Presence obj. $=0$ (room not occupied) <br> - Room temperature <br> < Desired room temperature during sun protection mode <br> Then heating by solar radiation should be favoured with the following setting. <br> Approach a preset position. Recommended for blinds, as height and slat turning can be set. <br> See Presets parameter page. <br> Recommended. <br> only for special applications. |
| Response when heating support is no longer needed | Preset 1, Preset 2 <br> Preset 3, Preset 4 <br> Preset 5, Preset 6 <br> Preset 7, Preset 8 <br> top end position <br> lower end position | Approach a preset position. See Presets parameter page. <br> Approach an end position. |

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| Designation | Values | Description |
| :---: | :---: | :---: |
|  | no reaction, unchanged <br> update <br> (height / slat) | Do not respond. <br> Approach last received position. |
| Response to cooling support | Preset 1, Preset 2 <br> Preset 3, Preset 4 <br> Preset 5, Preset 6 <br> Preset 7, Preset 8 <br> top end position <br> lower end position | If the conditions for cooling support are fulfilled, i.e.: <br> - Cooling support obj. =1 <br> - Room temperature > Desired room temperature during sun protection mode <br> Then heating by solar radiation should be prevented with the following setting. <br> Approach a preset position. Recommended for blinds, as height and slat turning can be set. <br> See Presets parameter page. only for special applications. <br> Recommended for roller blinds and textile sun protection. |
| Response when cooling support is no longer needed | Preset 1, Preset 2 <br> Preset 3, Preset 4 <br> Preset 5, Preset 6 <br> Preset 7, Preset 8 <br> top end position <br> lower end position <br> no reaction, unchanged <br> update <br> (height / slat) | Approach a preset position. See Presets parameter page. <br> Approach an end position. <br> Do not respond. <br> Approach last received position. |

(i) Ventilation function and heating/cooling support ${ }^{19}$ are mutually exclusive. If
ventilation is active ${ }^{20}$, no movements due to the heating/cooling support are executed,
but only after completion ${ }^{21}$ of the ventilation function ${ }^{22}$.
Vice versa, if ventilation is active at the end of heating/cooling support, the configured
action ${ }^{23}$ will not be executed.

[^5]
### 6.6.4 Positions via 1 bit

(1) 3 individually preallocated positions can be called up using 1-bit objects (objects position $A, B$ and $C$ ).

| Designation | Values | Description |
| :---: | :---: | :---: |
| Position A |  |  |
| Response when receiving a 1 | Preset 1 <br> Preset 2 <br> Preset 3 <br> Preset 4 <br> Preset 5 <br> Preset 6 <br> Preset 7 <br> Preset 8 <br> top end position <br> lower end position | Approach a preset position. See Presets parameter page. <br> Approach an end position. |
| Response when receiving a 0 | Preset 1 <br> Preset 2 <br> Preset 3 <br> Preset 4 <br> Preset 5 <br> Preset 6 <br> Preset 7 <br> Preset 8 <br> top end position <br> lower end position <br> no response <br> update (height / slat) | Approach a preset position. See Presets parameter page. <br> Approach an end position. <br> Do not respond. <br> Approach last received position. |
| Position B |  |  |
| Response when receiving a 1 | See above | Desired drive height or slat position for position B |
| Response when receiving a 0 | See above |  |
| Position C |  |  |
| Response when receiving a 1 | See above | Desired drive height or slat position for position C |
| Response when receiving a 0 | See above |  |

### 6.6.5 Ventilation

(1) With the ventilation function, the blinds or roller blinds are automatically moved to a defined position when opening or tilting the window.

| Designation | Values | Description |
| :---: | :---: | :---: |
| When the window is tilted |  |  |
| Approach ventilation position | Never <br> Always <br> Only when below | No change of position. <br> Always approach the preset position. <br> Do not take the current drive position into account. <br> Only approach the new position if the blinds or roller blinds position is lower than the desired ventilation position (preset). |
| Position | Preset 1 <br> Preset 2 <br> Preset 3 <br> Preset 4 <br> Preset 5 <br> Preset 6 <br> Preset 7 <br> Preset 8 <br> top end position <br> lower end position | Desired ventilation position. See Presets parameter page. <br> Approach an end position. |
| When the window is open |  |  |
| Approach ventilation position | Never <br> Always <br> Only when below | No change of position. <br> Always approach the preset position, do not take the current drive position into account <br> Only approach the new position if the blinds or roller blinds position is lower than the desired ventilation position (preset). |
| Position | Preset 1 <br> Preset 2 <br> Preset 3 <br> Preset 4 <br> Preset 5 <br> Preset 6 <br> Preset 7 <br> Preset 8 <br> top end position <br> lower end position | Desired ventilation position. See Presets parameter page. <br> Approach an end position. |


| Designation | Values | Description |
| :--- | :--- | :--- |
| Position after end of ventilation | Preset 1 <br> Preset 2 <br> Preset 3 <br> Preset 4 <br> Preset 5 <br> Preset 6 <br> Preset 7 <br> Preset 8 | Desired drive position when the <br> window is closed again. <br> See Presets parameter page. |
| Block comfort/auto during <br> ventilation | top end position <br> lower end position | no <br> via the height and slat objects. <br> Movement based on the height <br> and slat objects remains blocked, <br> until the window is closed again. <br> If Position after end of <br> ventilation = Update height and <br> slat is configured, the previously <br> received values will be <br> approached after the end of <br> ventilation. 24 |

(i) If the window is open/tilted while ventilation is blocked, the ventilation function will not be started.

If a block is set while the ventilation function is active, it will be abandoned. ${ }^{25}$

> (1) Ventilation function and heating/cooling support${ }^{26}$ are mutually exclusive. If ventilation is active ${ }^{27}$, no movements due to the heating/cooling support are executed, but only after completion ${ }^{28}$ of the ventilation function ${ }^{29}$. Vice versa, if ventilation is active at the end of heating/cooling support, the configured action ${ }^{30}$ will not be executed.

[^6]
### 6.6.5.1 Window contacts

The current window status is received via the objects Window contact 1 and Window contact 2. From the combination of both telegrams, the device can detect, whether the window is closed, tilted, or open.
(1) The status of the window contacts is exclusively received via the bus.

| Designation | Values | Description |
| :---: | :---: | :---: |
| Number of window contents for this window | 1 contact <br> 2 contacts (open/tilted) | Here, only 2 states are detected: window open / window closed. <br> The device can distinguish 3 states: closed - tilted - open. The corresponding switching statuses are defined below. |
| When the window is tilted |  |  |
| Status object window contact 1 | $\begin{aligned} & \text { Off } \\ & \text { On } \\ & \hline \end{aligned}$ | Combination at which the window is detected as "tilted". |
| Status object window contact 2 | $\begin{aligned} & \hline \text { Off } \\ & \text { On } \\ & \hline \end{aligned}$ |  |
| When the window is open |  |  |
| Status object window contact 1 | $\begin{aligned} & \text { Off } \\ & \text { On } \end{aligned}$ | Combination at which the status is detected as "open". |
| Status object window contact 2 | $\begin{aligned} & \hline \text { Off } \\ & \text { On } \\ & \hline \end{aligned}$ |  |
| Acting direction object window contact $7^{31}$ | 0 = window open or tilted $0=\text { window closed }$ | $0=\text { open }^{32} / 1 \text { = closed }$ $0=\text { closed } / 1=\text { open }^{33}$ |
| Block telegram | Block with 1 (standard) <br> Block with 0 | $\begin{aligned} & 0=\text { cancel block } \\ & 1=\text { block } \\ & 0=\text { block } \\ & 1 \text { = cancel block } \end{aligned}$ |

(i)

The input objects channel C1 - window contact 1 and channel C1 - window contact 2 are not connected to inputs 11 and I 2 internally.
The connection is exclusively implemented via bus telegrams. ${ }^{34}$ For this purpose, these objects are connected with the objects channel I1 - window contact 1 and channel 12 - window contact 2 via group addresses.
${ }^{31}$ If only one window contact is used.
${ }^{32}$ No differentiation between open and tilted possible.
${ }^{33} \mathrm{No}$ differentiation between open and tilted possible.
${ }^{34}$ Thus, the window status can be received either via the own inputs 11,12 , or from other bus sharing units (binary input, button interface, etc.).

### 6.6.6 Safety wind / rain / frost

| Designation | Values | Description |
| :---: | :---: | :---: |
| Priority of safety objects | 1. wind 2. rain, 3. frost <br> 1. wind, 2. frost, 3. rain <br> 1. rain, 2. wind, 3. frost <br> 1. rain, 2. frost, 3. wind <br> 1. frost, 2. wind, 3. rain <br> 1. frost, 2. rain, 3. wind | If wind, rain and frost alarm occur together, the parameters of the object with the highest priority will be implemented. Example: <br> 1. rain, 2. frost, 3. wind The parameters with priority 1 apply, i.e. start and end of rain safety. <br> If the rain alarm (priority 1) is cancelled, the parameters for the object with priority 2 apply, here frost - start. <br> If the object with priority 2 is also cancelled, the one with priority 3 applies. |
| Monitor safety objects cyclically | по <br> every 10 min every 20 min every 60 min | No monitoring. <br> After mains failure, the safety object will be reset to 0 . <br> Safety objects that do not receive any telegrams within the time set here will be handled as if they had received an ON telegram and trigger an alarm (e.g. WIND, etc.). <br> The sender of the safety telegrams (e.g. weather station) must transmit them cyclically. Max. cycle time $=$ monitoring time/2 <br> Example: <br> Monitoring time = every 20 minutes, cyclical transmission time $=10 \mathrm{~min}$ or less. |
| Participation in safety WIND | $\begin{aligned} & \text { yes } \\ & \text { no } \end{aligned}$ | Should the channel react to wind alarm? |
| Source(s) | Safety object 1 wind Safety object 2 wind Safety object 3 wind Safety object $1+2$ (OR linked) <br> Safety object $1+3$ (OR linked) <br> Safety object $2+3$ (OR linked) <br> safety object $1+2+3$ (OR linked) | Which safety objects are used for wind alarm? |
| Start |  | Start on wind alarm: |


| Designation | Values | Description |
| :---: | :---: | :---: |
|  | Preset 1 <br> Preset 2 <br> Preset 3 <br> Preset 4 <br> Preset 5 <br> Preset 6 <br> Preset 7 <br> Preset 8 <br> top end position <br> lower end position <br> unchanged (stopped <br> upon operating <br> command) | Approach a preset position. See parameter page Presets. <br> Approach an end position. <br> Do not respond. The drive should stop upon safety start during a movement. |
| End | same as before safety <br> Preset 1 <br> Preset 2 <br> Preset 3 <br> Preset 4 <br> Preset 5 <br> Preset 6 <br> Preset 7 <br> Preset 8 <br> top end position <br> lower end position <br> update (height / slat) <br> no response | End on wind alarm: move back to the previous position. <br> Approach a preset position. See parameter page Presets. <br> Approach an end position. <br> Approach last received position. <br> Do not respond. |
| Participation in safety RAIN | $\begin{aligned} & \text { yes } \\ & \text { no } \end{aligned}$ | Should the channel react to rain alarm? |
| Start | Preset 1 <br> Preset 2 <br> Preset 3 <br> Preset 4 <br> Preset 5 <br> Preset 6 <br> Preset 7 <br> Preset 8 <br> top end position <br> lower end position <br> unchanged <br> (stop upon operating <br> command) | Start on rain alarm: <br> Approach a preset position. <br> See Presets parameter page. <br> Approach an end position. <br> Do not respond. The drive should stop upon safety start during a movement. |
| End | same as before safety | End on rain alarm: move back to the previous position. |


| Designation | Values | Description |
| :---: | :---: | :---: |
|  | Preset 1 <br> Preset 2 <br> Preset 3 <br> Preset 4 <br> Preset 5 <br> Preset 6 <br> Preset 7 <br> Preset 8 top end position lower end position update (height / slat) <br> no response | Approach a preset position. See parameter page Presets. <br> Approach an end position. <br> Approach last received position. <br> Do not respond. |
| Participation in safety FROST | $\begin{array}{\|l\|} \hline \text { yes } \\ \text { no } \\ \hline \end{array}$ | Should the channel react to frost alarm? |
| Start | Preset 1 <br> Preset 2 <br> Preset 3 <br> Preset 4 <br> Preset 5 <br> Preset 6 <br> Preset 7 <br> Preset 8 top end position lower end position unchanged (stopped upon operating command) | Start on frost alarm: <br> Approach a preset position. <br> See parameter page Presets. <br> Approach an end position. <br> Do not respond. The drive should stop upon safety start during a movement. |
| End | same as before safety <br> Preset 1 <br> Preset 2 <br> Preset 3 <br> Preset 4 <br> Preset 5 <br> Preset 6 <br> Preset 7 <br> Preset 8 <br> top end position <br> lower end position <br> update (height / slat) <br> no response | End on frost alarm: move back to the previous position. <br> Approach a preset position. See parameter page Presets. <br> Approach an end position. <br> Approach last received position. <br> Do not respond. |


| Designation | Values | Description |
| :--- | :--- | :--- |
| Response after priority on safety |  | Priority on safety will be used <br> when the roller blinds or sun <br> protection devices must remain <br> stationary in an end position for <br> a certain time, e.g. for window <br> cleaning. <br> See object Priority on safety. <br> This operating mode has the <br> highest priority level. |
|  | Preset 7 <br> Preset 2 <br> Preset 3 <br> Preset 4 <br> Preset 5 <br> Preset 6 <br> Preset 7 <br> Preset 8 <br> top end position <br> lower end position <br> no reaction, unchanged <br> Approach a preset position. <br> update (height / slat) | Ape parameter page Presets. |
| un not respond. |  |  |
| Approach last received position. |  |  |

### 6.6.7 Presets

(1)

The presets are a predefined position settings, which can be called up if required, e.g. on safety (wind, rain, frost), on restoration of the bus supply, during ventilation, etc.

| Designation | Values | Description |
| :---: | :---: | :---: |
| Preset 1 |  |  |
| Position | $\begin{aligned} & 0 \%, 10 \%, 20 \% \\ & 30 \%, 40 \%, 50 \% \\ & 60 \%, 70 \%, 80 \% \\ & 90 \%, 100 \%, \\ & \text { no change } \end{aligned}$ | Desired drive height and slat position for preset 1 |
| Slat | $\begin{aligned} & 0 \%, 10 \%, 20 \% \\ & 30 \%, 40 \%, 50 \% \\ & 60 \%, 70 \%, 80 \% \\ & 90 \%, 100 \% \text {, } \\ & \text { no change } \end{aligned}$ |  |
| Preset 2 |  |  |
| Position | See above | Desired drive height and slat position for preset 2 |
| Slat | See above |  |
| Preset 3 |  |  |
| Position | See above | Desired drive height and slat position for preset 3 |
| Slat | See above |  |
| Preset 4 |  |  |
| Position | See above | Desired drive height and slat position for preset 4 |
| Slat | See above |  |
| Preset 5 |  |  |
| Position | See above | Desired drive height and slat position for preset 5 |
| Slat | See above |  |
| Preset 6 |  |  |
| Position | See above | Desired drive height and slat position for preset 6 |
| Slat | See above |  |
| Preset 7 |  |  |
| Position | See above | Desired drive height and slat position for preset 7 |
| Slat | See above |  |
| Preset 8 |  |  |
| Position | See above | Desired drive height and slat position for preset 8 |
| Slat | See above |  |

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### 6.6.8 Restoration of power

| Designation | Values | Description |
| :---: | :---: | :---: |
| Response in the event of bus failure ${ }^{35}$ | Up <br> Down <br> Stop | (i) <br> After a bus <br> failure, the device is no <br> longer supplied with power. <br> Therefore, the drive can only be stopped or moved up/down. ${ }^{36}$ <br> Raise. <br> Lower. <br> Stop drive. |
| Behaviour on restoration of the bus supply ${ }^{37}$ | Preset 1 <br> Preset 2 <br> Preset 3 <br> Preset 4 <br> Preset 5 <br> Preset 6 <br> Preset 7 <br> Preset 8 <br> top end position <br> lower end position <br> no response | After return of bus or mains voltage... <br> Approach a preset position. See Presets parameter page. <br> Approach an end position. <br> Do not respond. |

[^7]
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6.6.9 Block function

| Designation | Values | Description |
| :---: | :---: | :---: |
| Block telegram | Block with 1 (standard) <br> Block with 0 | $\begin{aligned} & 0=\text { cancel block } \\ & 1=\text { block } \\ & 0=\text { block } \\ & 1 \text { = cancel block } \end{aligned}$ <br> Note: The block is always deactivated after reset. |
| Response when the block is set | Preset 1 <br> Preset 2 <br> Preset 3 <br> Preset 4 <br> Preset 5 <br> Preset 6 <br> Preset 7 <br> Preset 8 <br> top end position <br> lower end position <br> unchanged (stopped <br> upon operating <br> command) | Approach a preset position. See Presets parameter page. <br> Approach an end position. <br> Do not respond. The drive should stop when a block command is received during a movement. |
| Response when the block is cancelled | Preset 1 <br> Preset 2 <br> Preset 3 <br> Preset 4 <br> Preset 5 <br> Preset 6 <br> Preset 7 <br> Preset 8 <br> top end position <br> lower end position <br> unchanged (stopped <br> upon operating <br> command) <br> update (height / slat) | Approach a preset position. See Presets parameter page. <br> Approach an end position. <br> Do not respond. The drive should stop when a block command is received during a movement. <br> Approach last received position. |

### 6.6.10 Scenes

| Designation | Values | Description |
| :---: | :---: | :---: |
| Block telegram for scenes | Block with 1 (standard) <br> Block with 0 | $\begin{aligned} & \hline 0=\text { cancel block } \\ & 1=\text { block } \end{aligned}$ $0 \text { = block }$ $1 \text { = cancel block }$ <br> Note: With this setting, the scenes are always blocked immediately after reset or download. |
| All channel scene statuses | Overwrite on download <br> Unchanged after download | A download deletes all scene memories in a channel, i.e. all previously taught-in scenes. When a scene number is called, the channel assumes the configured "Status after download" (see below). <br> See appendix: Teaching in scenes without telegrams <br> All previously taught-in scenes are saved. However, the scene numbers to which the channel should react can be changed (see below: Channel reacts to). |
| Participation in central scene object | $\begin{aligned} & \text { No } \\ & \text { yes } \end{aligned}$ | Should the device react to the central scene object? |
| Response when the scene is cancelled <br> (with scene value 63) | Preset 1 <br> Preset 2 <br> Preset 3 <br> Preset 4 <br> Preset 5 <br> Preset 6 <br> Preset 7 <br> Preset 8 <br> top end position <br> lower end position <br> no response <br> update (height ) <br> slat) | Behaviour when the object Call up/save scenes receives value 63 ( $\$ 3 \mathrm{~F}$ ) and thus the current scene is cancelled. <br> Approach a preset position. See Presets parameter page. <br> Approach an end position. <br> Do not respond. <br> Approach last received position. |
| 1st scene - preallocated with preset 1 |  |  |
| Channel reacts to | No scene number Scene number 1 ... <br> Scene number 63 | First of the 8 possible scene numbers to which the channel is to react. |
| Comment for this scene number | (Enter name) | Designation or comment for this scene number. |
| Block comfort/automatic during this scene | no | During this scene, the channel continues to react to height and slat telegrams |

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| Designation | Values | Description |
| :---: | :---: | :---: |
|  | yes | During this scene, the channel no longer reacts to height and slat telegrams. The Up/Down function is maintained. |
| Permit teach-in | по <br> yes | Scenes can only be called up. <br> The user can both call up and teach in or amend scenes. |
| 2nd scene - preallocated with preset 2 |  |  |
| Channel reacts to | No scene number Scene number 1 Scene number 2 <br> Scene number 63 | Second of the 8 possible scene numbers |
| Comment for this scene number | (Enter name) | See above. |
| Block comfort/automatic during this scene | $\begin{array}{\|l\|} \hline \text { no } \\ \text { yes } \\ \hline \end{array}$ | See above. |
| Permit teach-in | $\begin{array}{\|l} \hline \text { no } \\ \text { yes } \end{array}$ | See above. |
| 3rd scene - preallocated with preset 3 |  |  |
| Channel reacts to | No scene number Scene number 1 <br> Scene number 3 <br> Scene number 63 | Third of the 8 possible scene numbers |
| Comment for this scene number | (Enter name) | See above. |
| Block comfort/automatic during this scene | $\begin{array}{\|l\|} \hline \text { no } \\ \text { yes } \\ \hline \end{array}$ | See above. |
| Permit teach-in | $\begin{aligned} & \text { no } \\ & \text { yes } \end{aligned}$ | See above. |
| 4th scene - preallocated with preset 4 |  |  |
| Channel reacts to | No scene number Scene number 1 <br> Scene number 4 <br> Scene number 63 | Fourth of the 8 possible scene numbers |
| Comment for this scene number | (Enter name) | See above. |
| Block comfort/automatic during this scene | $\begin{array}{\|l} \hline \text { no } \\ \text { yes } \\ \hline \end{array}$ | See above. |
| Permit teach-in | $\begin{array}{\|l\|} \hline \text { no } \\ \text { yes } \\ \hline \end{array}$ | See above. |
| 5th scene - preallocated with preset 5 |  |  |
| Channel reacts to | No scene number Scene number 1 <br> Scene number 5 <br> Scene number 63 | Fifth of the 8 possible scene numbers |
| Comment for this scene number | (Enter name) | See above. |

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| Designation | Values | Description |
| :---: | :---: | :---: |
| Block comfort/automatic during this scene | $\begin{aligned} & \text { no } \\ & \text { yes } \\ & \hline \end{aligned}$ | See above. |
| Permit teach-in | $\begin{aligned} & \text { no } \\ & \text { yes } \end{aligned}$ | See above. |
| 6th scene - preallocated with preset 6 |  |  |
| Channel reacts to | No scene number Scene number 1 <br> Scene number 6 ... <br> Scene number 63 | Sixth of the 8 possible scene numbers |
| Comment for this scene number | (Enter name) | See above. |
| Block comfort/automatic during this scene | $\begin{aligned} & \text { no } \\ & \text { yes } \end{aligned}$ | See above. |
| Permit teach-in | $\begin{aligned} & \text { no } \\ & \text { yes } \end{aligned}$ | See above. |
| 7th scene - preallocated with preset 7 |  |  |
| Channel reacts to | No scene number Scene number 1 Scene number 7 <br> Scene number 63 | Seventh of the 8 possible scene numbers |
| Comment for this scene number | (Enter name) | See above. |
| Block comfort/automatic during this scene | $\begin{aligned} & \text { no } \\ & \text { yes } \end{aligned}$ | See above. |
| Permit teach-in | $\begin{aligned} & \text { no } \\ & \text { yes } \end{aligned}$ | See above. |
| 8th scene - preallocated with preset 8 |  |  |
| Channel reacts to | No scene number Scene number 1 <br> Scene number 8 <br> Scene number 63 | Last of the 8 possible scene numbers |
| Comment for this scene number | (Enter name) | See above. |
| Block comfort/automatic during this scene | $\begin{aligned} & \text { no } \\ & \text { yes } \end{aligned}$ | See above. |
| Permit teach-in | $\begin{aligned} & \text { no } \\ & \text { yes } \end{aligned}$ | See above. |

6.7 Parameters for the switch actuator

### 6.7.1 Channel C1 (C2): Configuration options

| Designation | Values | Description |
| :---: | :---: | :---: |
| Channel function | Switching on / off.. <br> On/off delay.. <br> Pulse function.. <br> Staircase light time switch with forewarning function.. Flashing.. | Determines the basic functionality of the channel. |
| Activation of function via | Switch object <br> Exceeding the threshold | The channel is operated via a 1-bit object. <br> The channel is operated through exceeding a 1- or 2byte threshold. See below: the Threshold parameter page |
| Adjust block function | Yes. <br> no | The block function can be individually adjusted. <br> The relevant parameter page is shown. <br> The block function works with the standard parameters: <br> - Block with 1 (standard) - When the block is set: Unchanged - When the block is cancelled: Update. |
| Activate scenes | Yes.. กо | Should scenes be used? |
| Participation in central objects | no | Central objects are not taken into account. |

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| Designation | Values | Description |
| :---: | :---: | :---: |
|  | in central switching, permanent ON, permanent OFF <br> only in central permanent ON <br> only in central permanent OFF <br> only in central switching only in central switching and permanent ON only in central switching and permanent OFF only in central permanent ON and permanent OFF | Which central objects are to be taken into account? <br> Central objects enable simultaneous switching on and off of several channels with one single object. |
| Adjust feedback | Yes.. <br> по | The feedback function can be individually adjusted. <br> The relevant parameter page is shown. <br> The Feedback function works with the standard parameters: <br> - not inverted <br> - do not send cyclically |
| Activate hour counter | Yes.. กо | Is the hour counter/service interval function to be used? |
| Activate link | Yes.. <br> no | Use logical links with the channel object? |

### 6.7.2 Contact characteristics

| Designation | Values | Description |
| :---: | :---: | :---: |
| Type of contact | NO contact <br> NC contact | Standard: <br> The relay contact is closed when a switchon command is issued. <br> Inverted: <br> The relay contact is opened when a switchon command is issued. |
| Status with download and bus failure | OFF <br> ON <br> unchanged | After download or with bus voltage failure... ..the relay switches off. ..the relay switches on. ...the relay remains in the same state as before. <br> If several switching operations were executed immediately before the bus failure, the energy may not be sufficient for an additional switching operation. <br> In this case, the relay remains in its previous state, regardless of the parameter setting. |
| Status with restoration of the bus supply | OFF <br> ON <br> same as before <br> failure | After return of bus voltage... ..the relay is switched off. ..the relay switches on. ...the relay remains in the same state as before. |

### 6.7.3 The "On/off delay.." time function

This parameter page appears if On/off delay is chosen as the Channel function.

| Designation |  | Values |
| :--- | :--- | :--- |
| Switch-on delay |  | $0 . .3$ |
| Hours | $0 . .60$ | Input of desired switch-on delay in <br> hours. |
| Minutes | $0 . .255$ | Input of desired switch-on delay in <br> minutes. |
| Seconds | $0 . .3$ | Input of desired switch-on delay in <br> seconds. |
| Switch-off delay | $0 . .60$ | Input of desired switch-off delay in <br> hours. |
| Hours | Input of desired switch-off delay in <br> minutes. |  |
| Minutes | $0 . .255$ | Input of desired switch-off delay in <br> seconds. |
| Seconds |  |  |

### 6.7.4 The "Pulse" time function

This parameter page appears if Pulse function is chosen as the Channel function.

| Designation | Values | Description |
| :--- | :--- | :--- |
| Hours | $0 . .3$ | Input of desired pulse duration in <br> hours. |
| Minutes | $0 . .60$ | Input of desired pulse duration in <br> minutes. |
| Seconds | $0 . .255$ | Input of desired pulse duration in <br> seconds. |
| Pulse can be retriggered <br> (with 1 on switch object) | Yes | The pulse can be extended <br> as often as desired via a 1-telegram |
| Pulse can be reset <br> (with 1 on switch object) | Yes pulse cannot be extended. |  |$|$| The pulse can be ended early at any |
| :--- |
| time |
| via a 0-telegram. |
| The pulse cannot be ended early |

### 6.7.5 The "Staircase light with forewarning function .." time function

This parameter page appears if Staircase light with forewarning function is chosen as the Channel function.
The user can press a button again to extend the staircase light time at any time.

| Designation | Values | Description |
| :--- | :--- | :--- |
| Staircase light time (min. 1 s) | $0 . .3$ | Input of desired switch-on delay in <br> hours. |
| Hours | $0 . .60$ | Input of desired switch-on delay in <br> minutes. |
| Minutes | $0 . .255$ | Input of desired switch-on delay in <br> seconds. |
| Seconds | 0 | Determines how often the staircase <br> light time can be extended <br> (restarted) by pressing the button <br> again. |
| The maximum sum of pulses | ...40 <br> Default value $=5$ | The light switches off immediately <br> once the staircase light time is <br> completed. |
| Duration of <br> 1st forewarning in s | 1..60 <br> Default value $=10$ <br> Once the staircase light time is <br> completed, the light should flash <br> briefly and then stay on for the <br> duration of the forewarning |  |
| Duration of <br> 2nd forewarning in s | 0 | No 2nd forewarning. <br> The light switches off at the end of <br> the 1st forewarning. |

## Example: forewarning function

| Staircase light time |  | 1nd forewarning | 号 | 2nd <br> forewarning | OFF |
| :---: | :---: | :---: | :---: | :---: | :---: |

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### 6.7.6 The "Flashing" time function

This parameter page appears if Flashing is chosen as the Channel function.

| Designation | Values | Description |
| :---: | :---: | :---: |
| ON phase of flash pulse |  |  |
| Hours | $0 . .3$ | Input of desired pulse time in hours. |
| Minutes | $0 . .60$ | Input of desired pulse time in minutes. |
| Seconds | $0 . .255$ | Input of desired pulse time in seconds. |
| OFF phase of flash pulse |  |  |
| Hours | $0 . .3$ | Input of desired length of break in hours. |
| Minutes | $0 . .60$ | Input of desired length of break in minutes. |
| Seconds | $0 . .255$ | Input of desired length of break in seconds. |
| How often should it flash | Until it switches off <br> $1 x$ <br> $2 x$ <br> $3 x$ <br> $4 x$ <br> $5 x$ <br> $7 x$ <br> $10 x$ <br> $15 x$ <br> $20 x$ <br> $30 x$ <br> $50 x$ | The channel flashes until a switchoff telegram is received. <br> The channel flashes as often as set here. |

### 6.7.7 Threshold

This page is shown if the Activation of the function by exceeding threshold parameter is set.

| Designation | Values | Description |
| :---: | :---: | :---: |
| Type of threshold object | Per cent (DPT5.001) <br> Counter value 0.255 <br> (DPT 5.010) <br> Counter value <br> 0.. 65535 (DPT 7.001) <br> Floating-point number (DPT9), e.g. temperature, brightness, etc. | Threshold format |
| Parameter for threshold object Per cent |  |  |
| Threshold | $\begin{aligned} & \text { 1..99\% } \\ & \text { Default value = 50\% } \end{aligned}$ | Desired threshold. <br> Example of NO contact with response as switch object = 1: <br> Switches on when: <br> Object value > threshold <br> Switches off when: <br> Object value < threshold - hysteresis |
| Hysteresis (as \%) | $\begin{aligned} & \text { 1..99\% } \\ & \text { Default value = 10\% } \end{aligned}$ | The hysteresis prevents frequent switching after small fluctuations in readings. |
| Parameter for threshold object Counter value $0 . .255$ |  |  |
| Threshold | $\begin{aligned} & \text { 1.. } 254 \\ & \text { Default value }=127 \end{aligned}$ | Desired threshold. <br> Example of NO contact with response as switch object = 1: <br> Switches on when: <br> Object value > threshold <br> Switches off when: <br> Object value < threshold - hysteresis |
| Hysteresis | 1. 254 <br> Default value $=5$ | The hysteresis prevents frequent switching after small fluctuations in readings. |
| Parameter for threshold object Counter value $0 . .65535$ |  |  |
| Threshold | $\begin{aligned} & \text { 1.. } 65534 \\ & \text { Default value }=1000 \end{aligned}$ | Desired threshold. <br> Example of NO contact with response as switch object = 1: <br> Switches on when: <br> Object value > threshold <br> Switches off when: <br> Object value < threshold - hysteresis |
| Hysteresis | 1.. 65534 Default value $=5$ | The hysteresis prevents frequent switching after small fluctuations in readings. |
| Parameter for threshold object Floating-point number (DPT9), e.g. temperature, brightness, etc.) |  |  |
| Threshold | $\begin{aligned} & \hline-671088.64 . . \\ & \text { 670760.96 } \\ & \text { Default value }=20 \end{aligned}$ | Desired threshold. <br> Example of NO contact with response as switch object = 1: <br> Switches on when: <br> Object value > threshold <br> Switches off when: <br> Object value < threshold - hysteresis |


| Designation | Values | Description |
| :--- | :--- | :--- |
| Hysteresis | 0.01.. <br> 670760.96 <br> Default value =1 | The hysteresis prevents frequent switching <br> after small fluctuations in readings. |
| Response on exceeding the <br> threshold | As switch object = 0 | Should the channel switch on or off on <br> exceeding the threshold? <br> The set type of contact must be taken into <br> account here. |
|  | NO contact: the relay switches off if |  |
| threshold is exceeded. |  |  |
| NC contact: the relay switches on if |  |  |
| threshold is exceeded. |  |  |

### 6.7.8 Block function

This page appears when "Adjust block function" is selected on the Configuration options parameter page.

| Designation | Values | Description |
| :---: | :---: | :---: |
| Block telegram | Block with 1 (standard) <br> Block with 0 | $\begin{aligned} & 0=\text { cancel block } \\ & 1=\text { block } \\ & 0=\text { block } \\ & 1=\text { cancel block } \end{aligned}$ <br> Note: The block is always deactivated after reset. |
| Response when the block is set | OFF <br> ON <br> unchanged | Switch off Switch on <br> No response |
| Response when the block is cancelled | OFF <br> ON <br> unchanged <br> update | Switch off <br> Switch on <br> No response <br> Restore normal operation and switch relay accordingly. |

### 6.7.9 Scenes

This page appears when the scenes are activated on the Configuration options parameter page. Each channel can participate in up to 8 scenes.

| Designation | Values | Description |
| :---: | :---: | :---: |
| Block telegram for scenes | Block with 1 (standard) <br> Block with 0 | $\begin{array}{\|l} \hline 0 \text { = cancel block } \\ 1 \text { = block } \\ 0=\text { block } \\ 1=\text { cancel block } \\ \text { Note: With this setting, the scenes } \\ \text { are always blocked immediately after } \\ \text { reset or download. } \\ \hline \end{array}$ |
| All channel scene statuses | Overwrite on download <br> Unchanged after download | A download deletes all scene memories in a channel, i.e. all previously taught-in scenes. When a scene number is called, the channel assumes the configured "Status after download" (see below). See appendix: Teaching in scenes without telegrams <br> All previously taught-in scenes are saved. <br> However, the scene numbers to which the channel should react can be changed (see below: Channel reacts to). |
| Participation in central scene object | $\begin{aligned} & \text { No } \\ & \text { yes } \end{aligned}$ | Should the device react to the central scene object? |
| Channel reacts to | No scene number Scene number 1 <br> Scene number 63 | First of the 8 possible scene numbers to which the channel is to react. |
| Status after download | $\begin{aligned} & \text { Off } \\ & \text { On } \end{aligned}$ | New switching status which is to be allocated to the selected scene number. <br> Only possible if the scene statuses are to be overwritten after download. |
| Permit teach-in | No <br> Yes | Scenes can only be called up. <br> The user can both call up and teach in or amend scenes. |
| Channel reacts to | No scene number Scene number 1 Scene number 2 <br> Scene number 63 | Second of the 8 possible scene numbers |
| Status after download | Off | See above. |

## theben

| Designation | Values | Description |
| :---: | :---: | :---: |
|  | On |  |
| Permit teach-in | $\begin{aligned} & \text { No } \\ & \text { Yes } \end{aligned}$ | See above. |
| Channel reacts to | No scene number Scene number 1 <br> Scene number 3 ... <br> Scene number 63 | Third of the 8 possible scene numbers |
| Status after download | $\begin{aligned} & \text { Off } \\ & \text { On } \end{aligned}$ | See above. |
| Permit teach-in | $\begin{aligned} & \hline \text { No } \\ & \text { Yes } \\ & \hline \end{aligned}$ | See above. |
| Channel reacts to | No scene number Scene number 1 Scene number 4 ... <br> Scene number 63 | Fourth of the 8 possible scene numbers |
| Status after download | Off | See above. |
| Permit teach-in | $\begin{aligned} & \text { No } \\ & \text { Yes } \end{aligned}$ | See above. |
| Channel reacts to | No scene number Scene number 1 <br> Scene number 5 <br> Scene number 63 | Fifth of the 8 possible scene numbers |
| Status after download | $\begin{aligned} & \text { Off } \\ & \text { On } \\ & \hline \end{aligned}$ | See above. |
| Permit teach-in | $\begin{array}{\|l\|} \hline \text { No } \\ \text { Yes } \\ \hline \end{array}$ | See above. |
| Channel reacts to | No scene number Scene number 1 Scene number 6 ... <br> Scene number 63 | Sixth of the 8 possible scene numbers |
| Status after download | $\begin{aligned} & \text { Off } \\ & \text { On } \end{aligned}$ | See above. |
| Permit teach-in | No Yes | See above. |
| Channel reacts to | No scene number Scene number 1 <br> Scene number 7 | Seventh of the 8 possible scene numbers |


| Designation | Values | Description |
| :--- | :--- | :--- |
|  | Scene number 63 |  |
| Status after download | Off <br> On | No <br> Yes |
| Permit teach-in | No scene number <br> Scene number 1 <br> $\ldots$ <br> Scene number 8 | Last of the 8 possible scene numbers |
| Channel reacts to | $\ldots$ <br> Scene number 63 |  |
| Status after download | Off <br> On | See above. |
| Permit teach-in | No <br> Yes | See above. |

6.7.10 Feedback

| Designation | Values | Description |
| :--- | :--- | :--- |
| Reported status | Not inverted | Channel switched on: <br> feedback object sends a <br> 1 |
|  | inverted | Channel switched on: <br> feedback object sends a <br> 0 |
| Transmit feedback cyclically | No <br> yes | Send at regular <br> intervals? |
| Time for cyclical transmission <br> of feedback | 2 minutes, 3 minutes, <br> 5 minutes, 10 minutes, | At what interval? |
|  | 15 minutes, 20 minutes, |  |
|  | 30 minutes, 45 minutes |  |
| 60 minutes |  |  |$\quad$.

### 6.7.11 Hour counter and service

This page appears when Activate hour counter is selected on the Configuration options parameter page.

| Designation | Values | Description |
| :---: | :---: | :---: |
| Type of hour counter | Hour counter <br> Counter for time to next service | Forward counter for channel duty cycle. <br> Backward counter for channel duty cycle. |
| Hour counter |  |  |
| Reporting of operating hours in the event of a change (0.. 100 h, $0=$ no report) | $\begin{aligned} & 0 . .100 \\ & \text { Default value }=10 \end{aligned}$ | At what interval is the current counter reading to be sent? <br> Example: <br> $10=$ Send each time the counter reading increases by another 10 hours. |
| Report operating hours cyclically | No <br> yes | Send at regular intervals? |
| Time for cyclical transmission | 2 minutes, 3 minutes, 5 minutes, 10 minutes, 15 minutes, 20 minutes, 30 minutes, 45 minutes 60 minutes | At what interval? |
| Counter for time to next service |  |  |
| Service interval $(x 10 \mathrm{~h})$ | $\begin{aligned} & \text { O. } 2000 \\ & \text { Default value }=100 \end{aligned}$ | Desired timescale between 2 services. <br> Example: $\begin{aligned} & 10=10 \times 10 \mathrm{~h} \\ & =100 \text { hours } \\ & \hline \end{aligned}$ |
| Reporting of time to service in the event of a change (0 = no report) | $\begin{aligned} & \text { O.. } 100 \\ & \text { Default value = } 10 \end{aligned}$ | At what interval is the current counter reading to be sent? <br> Example: <br> $10=$ Send each time the counter reading decreases by another 10 hours. |
| Report time to service cyclically | $\begin{aligned} & \text { no } \\ & \text { Yes } \end{aligned}$ | Send remaining time to next service at regular intervals? <br> $\rightarrow$ Object Time to next service. |
| Report service cyclically | $\begin{aligned} & \text { no } \\ & \text { Yes } \end{aligned}$ | Send expiry of time to next service at regular intervals? <br> $\rightarrow$ Object Service required. |
| Time for cyclical transmission (if used) | 2 minutes, 3 minutes, 5 minutes, 10 minutes, 15 minutes, 20 minutes, 30 minutes, 45 minutes 60 minutes | At what interval? |

6.7.12 Link

| Designation | Values | Description |
| :--- | :--- | :--- |
| Activate link | OND link | Selection of logical link with the <br> input object <br> The Logic input in AND gate |
| object appears. |  |  |
| The Logic input in OR gate object |  |  |
| appears. |  |  |
| The Logic input in XOR gate |  |  |
| object appears. |  |  |$|$| Block object affects logic object | No link | The block object only affects the <br> input object. <br> If required, the logic object can <br> activate the channel function <br> despite block (with OR and XOR <br> link). <br> The block object affects the input <br> object and the logic object. <br> The channel function is <br> completely blocked if the block is <br> active. |
| :--- | :--- | :--- |

### 6.8 Parameters for the external inputs 11 , 12 purely as KNX binary inputs

(i) If direct control is not required, inputs I1 and I2 are available as KNX binary inputs.


The parameter Control channel C1 directly ${ }^{38}$ must be set to no for this purpose.

### 6.8.1 Input 11, I2: Switch function

| Designation | Values | Description |
| :---: | :---: | :---: |
| Function | Switch.. ${ }^{39}$ <br> Button.. <br> Dimming. <br> Blinds.. <br> Window contact. | Desired use. |
| Control channel C1 directly | yes <br> No | 11 is used exclusively as an input for switch actuator channel C1. I1 is connected to C1 internally and has no communication objects. <br> 11 is used purely as a KNX binary input. <br> There is no internal connection to the switch actuator. |
| Debounce time | $\begin{aligned} & 30 \mathrm{~ms}, 50 \mathrm{~ms}, 80 \mathrm{~ms} \\ & 100 \mathrm{~ms}, 200 \mathrm{~ms} \text {, } \\ & 1 \mathrm{~s}, 5 \mathrm{~s}, 10 \mathrm{~s} \end{aligned}$ | In order to avoid disruptive switching due to bouncing of the contact connected to the input, the new status of the input is only accepted after a delay time. Larger values ( $\geq 1 \mathrm{~s}$ ) can be used as a switch-on delay |
| Activate block function | no <br> yes | No block function. <br> Show parameters for the block function. |
| Block telegram | Block with 1 (standard) <br> Block with 0 | $\begin{aligned} & 0=\text { cancel block } \\ & 1=\text { block } \\ & 0=\text { block } \\ & 1=\text { cancel block } \end{aligned}$ |

${ }^{38}$ If necessary, control C2 directly.
${ }^{39}$ Direct control of C1 possible (switch actuator).
${ }^{40}$ Direct control of C1 possible (switch actuator).
${ }^{41}$ Direct control of C1 possible (blind actuator).

| Designation | Values | Description |
| :--- | :--- | :--- |
| Send cyclically | every min <br> every 2 min <br> every 3 min <br> $\ldots$ <br> every 30 min <br> every 45 min <br> every 60 min | Common cycle time for all 3 <br> output objects of the channel. |
| Number of telegrams | one telegram <br> two telegrams | Each channel has 2 output <br> objects and can thus send up to <br> 2 different telegrams. |

### 6.8.1.1 Switch objects 1, 2

Each of the 2 objects can be configured individually on its own parameter page.

| Designation | Values | Description |  |
| :---: | :---: | :---: | :---: |
| Object type | Switching (1 bit) <br> Priority (2 bit) <br> Value 0-255 <br> Percentage value (1 byte) | Telegram type for this object. |  |
| Send if input = 1 | $\begin{aligned} & \text { no } \\ & \text { yes } \end{aligned}$ | Send if voltage is present at the input? |  |
| Telegram | With object type = switching 1 bit |  |  |
|  | ON OFF <br> INVERT | Send switch-on command Send switch-off command Invert current state (ON-OFF-ON etc.) |  |
|  | With object type = priority 2 bit |  |  |
|  |  | Function | Value |
|  | inactive | Priority inactive (no control) | 0 (00bin) |
|  | ON | Priority ON (control: enable, on) | 3 (11 bin) |
|  | OFF | Priority OFF (control: disable, off) | $2(10$ bin $)$ |
|  | With object type = value 0-255 |  |  |
|  | 0-255 | Any value between 0 and 255 can be sent. |  |
|  | With object type = percentage value 1 byte |  |  |
|  | 0-100\% | Any percentage value between 0 and $100 \%$ can be sent. |  |
| Send if input = 0 | $\begin{aligned} & \text { no } \\ & \text { yes } \end{aligned}$ | Send if no voltage is present at the input? |  |
| Telegram | See above: Same object type as Send if input = 1 |  |  |
| Send cyclically | no yes, always only if input $=1$ only if input $=0$ | When should cyclical sending take place? <br> The cycle time is set on the main parameter page of the channel. |  |
| Response after restoration of the bus supply ${ }^{42}$ | none <br> update (immediately) <br> update (after 5 s) <br> update (after 10 s ) <br> update (after 15 s ) | Do not send. <br> Send update telegram immediately or with delay. |  |
| Response when the block is set | Ignore block <br> no response <br> as with input $=1$ | The block function is ineffective with this telegram. <br> Do not respond when the block is set. <br> Respond as with rising edge. |  |

[^8]| Designation | Values | Description |
| :--- | :--- | :--- |
|  | as with input $=0$ | Respond as with falling edge. |
| Response when the <br> block is cancelled | no response | Do not respond when the block is <br> cancelled. <br> Send update telegram. |

### 6.8.2 Input 11, I2: Button function

| Designation | Values | Description |
| :---: | :---: | :---: |
| Function | Switch.. ${ }^{43}$ <br> Button.. ${ }^{4}$ <br> Dimming. <br> Blinds.. <br> Window contact | Desired use. |
| Control channel C1 directly | yes <br> No | 11 is used exclusively as an input for switch actuator channel C1. I1 is connected to C1 internally and has no communication objects. <br> 11 is used purely as a KNX binary input. There is no internal connection to the switch actuator. |
| Debounce time | $30 \mathrm{~ms}, 50 \mathrm{~ms}, 80 \mathrm{~ms}$ $100 \mathrm{~ms}, 200 \mathrm{~ms}$, $1 \mathrm{~s}, 5 \mathrm{~s}, 10 \mathrm{~s}$ | In order to avoid disruptive switching due to bouncing of the contact connected to the input, the new status of the input is only accepted after a delay time. Larger values ( $\geq 1 \mathrm{~s}$ ) can be used as a switch-on delay |
| Connected button | NO contact NC contact | Set the type of connected contact. |
| Long button push starting at | $300 \mathrm{~ms}, 400 \mathrm{~ms}$ $500 \mathrm{~ms}, 600 \mathrm{~ms}$ $700 \mathrm{~ms}, 800 \mathrm{~ms}$ $900 \mathrm{~ms}, 1 \mathrm{~s}$ | Serves to clearly differentiate between long and short button push. <br> If the button is pressed for at least as long as the set time, then a long button push will be registered. |
| Time for double-click | $\begin{aligned} & 300 \mathrm{~ms}, 400 \mathrm{~ms} \\ & 500 \mathrm{~ms}, 600 \mathrm{~ms} \\ & 700 \mathrm{~ms}, 800 \mathrm{~ms} \\ & 900 \mathrm{~ms}, 1 \mathrm{~s} \end{aligned}$ | Serves to differentiate between a double-click and 2 single clicks. Time period in which the second click must begin, in order to recognise a double-click. |
| Send cyclically | every min every 2 min every 3 min every 30 min every 45 min every 60 min | Common cycle time for all 2 output objects of the channel. |
| Number of telegrams | one telegram two telegrams | Each channel has 2 output objects and can thus send up to 2 different telegrams. |

[^9]| Designation | Values | Description |
| :--- | :--- | :--- |
| Activate block function | no | No block function. <br> Show parameters for the block <br> function. |
| Block telegram | yes | $0=$ cancel block <br> $1=$ block |
|  | Block with 1 (standard) |  |
|  | $0=$ block <br> $1=$ a cancel block |  |

## theben

6.8.2.1 Button objects 1, 2

| Designation | Values | Description |  |
| :---: | :---: | :---: | :---: |
| Object type | Switching (1 bit) <br> Priority (2 bit) <br> Value 0-255 <br> Percentage value (1 byte) | Telegram type for this object. |  |
| Send after short operation | do not send Send telegram | Respond to short button push? |  |
| Telegram | With object type = switching 1 bit |  |  |
|  | ON OFF <br> INVERT | Send switch-on command Send switch-off command Invert current state (ON-OFF-ON etc.) |  |
|  | With object type = priority 2 bit |  |  |
|  |  | Function | Value |
|  | inactive | Priority inactive (no control) | 0 ( 00 bin ${ }^{\text {a }}$ |
|  | ON | Priority ON (control: enable, on) | 3 (11 bin) |
|  | OFF | Priority OFF (control: disable, off) | $2(10$ bin $)$ |
|  | With object type = value 0-255 |  |  |
|  | 0-255 | Any value between 0 and 255 can be sent. |  |
|  | With object type = percentage value 1 byte |  |  |
|  | 0-100\% | Any percentage value between 0 and 100\% can be sent. |  |
| Send after long operation | do not send Send telegram | Respond to long button push? |  |
| Telegram | See above: Same object type as with short operation. |  |  |
| Send after double-click | do not send Send telegram | Respond to double-click? |  |
| Telegram | See above: Same object type as with short operation. |  |  |
| Send cyclically | $\begin{aligned} & \text { no } \\ & \text { yes } \end{aligned}$ | The cycle time is set on the main parameter page of the channel. |  |
| Response after restoration of the bus | none | Do not send. |  |


| Designation | Values | Description |
| :---: | :---: | :---: |
| supply ${ }^{45}$ | As with short (immediately) <br> As with short (after 5 s) <br> As with short (after 10 s ) <br> As with short (after 15 s) <br> As with long (immediately) <br> As with long (after 5 s) <br> As with long (after 10 s ) <br> As with long (after 15 s ) <br> As with double-click (immediately) <br> As with double-click (after 5 s) <br> As with double-click (after 10 s ) <br> As with double-click (after 15 s) | Send update telegram immediately or with delay. The value to be sent depends on the value configured for long button push, short button push or double-click. |
| Response when the block is set | Ignore block <br> no response <br> as with short <br> as with long <br> as with double-click | The block function is ineffective with this telegram. <br> Do not respond when the block is set. <br> Respond as with a short button push. <br> Respond as with a long button push. <br> Respond as with a double-click. |
| Response when the block is cancelled | no response <br> as with short <br> as with long <br> as with double-click | Do not respond when the block is cancelled. <br> Respond as with a short button push. <br> Respond as with a long button push. <br> Respond as with a double-click. |

## theben

### 6.8.3 Input 11, I2: Dimming function

| Designation | Values | Description |
| :---: | :---: | :---: |
| Channel function | Switch.. <br> Button.. <br> Dimming.. <br> Blinds.. <br> Window contact. | The input controls a dimming actuator, |
| Control channel C1 directly | No | I1 is used purely as a KNX binary input. <br> There is no internal connection to the switch actuator. |
| Debounce time | $30 \mathrm{~ms}, 50 \mathrm{~ms}, 80 \mathrm{~ms}$ $100 \mathrm{~ms}, 200 \mathrm{~ms}$, $1 \mathrm{~s}, 5 \mathrm{~s}, 10 \mathrm{~s}$ | In order to avoid disruptive switching due to bouncing of the contact connected to the input, the new status of the input is only accepted after a delay time. Larger values ( $\geq 1 \mathrm{~s}$ ) can be used as a switch-on delay |
| Activate block function | по yes | No block function. <br> Show block function parameter page. |
| Block telegram | Block with 1 (standard) <br> Block with 0 | $\begin{aligned} & 0=\text { cancel block } \\ & 1 \text { = block } \\ & 0=\text { block } \\ & 1=\text { cancel block } \end{aligned}$ |
| Long button push starting at | $300 \mathrm{~ms}, 400 \mathrm{~ms}$ $500 \mathrm{~ms}, 600 \mathrm{~ms}$ $700 \mathrm{~ms}, 800 \mathrm{~ms}$ $900 \mathrm{~ms}, 1 \mathrm{~s}$ | Serves to clearly differentiate between long and short button push. <br> If the button is pressed for at least as long as the set time, then a long button push will be registered. |
| Double-click additional function | по yes | No double-click function <br> The double-click parameter page is shown. |
| Time for double-click | $300 \mathrm{~ms}, 400 \mathrm{~ms}$ $500 \mathrm{~ms}, 600 \mathrm{~ms}$ $700 \mathrm{~ms}, 800 \mathrm{~ms}$ $900 \mathrm{~ms}, 1 \mathrm{~s}$ | Serves to differentiate between a double-click and 2 single clicks. Time period in which the second click must begin, in order to recognise a double-click. |

## theben

### 6.8.3.1 Double-click parameter page

| Designation | Values | Description |  |
| :---: | :---: | :---: | :---: |
| Object type | Switching (1 bit) <br> Priority (2 bit) <br> Value 0-255 <br> Percentage value (1 byte) | Telegram type for this object. |  |
| Telegram | With object type = switching 1 bit |  |  |
|  | $O N$ OFF <br> INVERT | Send switch-on command Send switch-off command Invert current state (ON-OFF-ON etc.) |  |
|  | With object type = priority 2 bit |  |  |
|  |  | Function | Value |
|  | inactive | Priority inactive (no control) | 0 (00bin) |
|  | ON | Priority ON (control: enable, on) | 3 (11 bin) |
|  | OFF | Priority OFF (control: disable, off) | 2 (10bin) |
|  | With object type = value 0-255 |  |  |
|  | 0-255 | Any value between 0 and 255 can be sent. |  |
|  | With object type $=$ percentage value 1 byte |  |  |
|  | 0-100\% | Any percentage value between 0 and $100 \%$ can be sent. |  |
| Send cyclically | do not send cyclically every min every 2 min every 3 min ... <br> every 45 min <br> every 60 min | How often should it be resent? |  |
| Response after restoration of the bus supply ${ }^{46}$ | none <br> As with double-click (immediately) <br> As with double-click (after 5 s) <br> As with double-click (after 10 s ) <br> As with double-click (after 15 s) | Do not send. <br> Send update telegram immediately or with delay. The value to be sent depends on the value configured for doubleclick. |  |
| Response when the block is set | Ignore block <br> no response <br> as with double-click | The block function is with this telegram. <br> Do not respond when set. <br> Respond as with a do | ffective <br> he block is <br> le-click. |

[^10]| Designation | Values | Description |
| :--- | :--- | :--- |
| Response when the <br> block is cancelled | no response | Do not respond when the block is <br> cancelled. |
|  | as with double-click | Respond as with a double-click. |

### 6.8.3.2 Dimming parameter page



[^11]| Designation | Values | Description |
| :---: | :---: | :---: |
|  | ON <br> OFF <br> ON after 5 s <br> ON after 10 s <br> ON after 15 s <br> OFF after 5 s <br> OFF after 10 s <br> OFF after 15 s | Switch on dimmer <br> Switch off dimmer <br> Switch on dimmer with delay <br> Switch off dimmer with delay |
| Response when the block is set | Ignore block <br> no response <br> ON <br> OFF | The block function is ineffective with this telegram. <br> Do not respond when the block is set. <br> Switch on dimmer <br> Switch off dimmer |
| Response when the block is cancelled | no response <br> ON <br> OFF | Do not respond when the block is cancelled. <br> Switch on dimmes <br> Switch off dimmer |

### 6.8.4 Input 11, I2: Blinds function

| Designation | Values | Description |
| :---: | :---: | :---: |
| Activate channel | $\begin{aligned} & \text { no } \\ & \text { yes } \end{aligned}$ | Use input? |
| Channel function | Switch.. <br> Button.. <br> Dimming.. <br> Blinds.. <br> Window contact. | The input controls a blind actuator. |
| Control channel C1 directly | yes <br> No | 11 is used exclusively as an input for blind actuator channel C1. I1 is connected to C1 internally and has no communication objects. <br> I1 is used purely as a KNX binary input. <br> There is no internal connection to the switch actuator. |
| Debounce time | $\begin{aligned} & 30 \mathrm{~ms}, 50 \mathrm{~ms}, 80 \mathrm{~ms} \\ & 100 \mathrm{~ms}, 200 \mathrm{~ms} \\ & 1 \mathrm{~s}, 5 \mathrm{~s}, 10 \mathrm{~s} \end{aligned}$ | In order to avoid disruptive switching due to bouncing of the contact connected to the input, the new status of the input is only accepted after a delay time. Larger values ( $\geq 1 \mathrm{~s}$ ) can be used as a switch-on delay. |
| Activate block function | no <br> yes | No block function. <br> Show block function parameter page. |
| Block telegram | Block with 1 (standard) <br> Block with 0 | $\begin{aligned} & 0=\text { cancel block } \\ & 1=\text { block } \\ & 0=\text { block } \\ & 1=\text { cancel block } \end{aligned}$ |
| Long button push starting at | $\begin{aligned} & 300 \mathrm{~ms}, 400 \mathrm{~ms} \\ & 500 \mathrm{~ms}, 600 \mathrm{~ms} \\ & 700 \mathrm{~ms}, 800 \mathrm{~ms} \\ & 900 \mathrm{~ms}, 1 \mathrm{~s} \end{aligned}$ | Serves to clearly differentiate between long and short button push. <br> If the button is pressed for at least as long as the set time, then a long button push will be registered. |
| Double-click additional function | по yes | No double-click function <br> The double-click parameter page is shown. |
| Time for double-click | $300 \mathrm{~ms}, 400 \mathrm{~ms}$ $500 \mathrm{~ms}, 600 \mathrm{~ms}$ $700 \mathrm{~ms}, 800 \mathrm{~ms}$ $900 \mathrm{~ms}, 1 \mathrm{~s}$ | Serves to differentiate between a double-click and 2 single clicks. Time period in which the second click must begin, in order to recognise a double-click. |

### 6.8.4.1 Double-click parameter page

| Designation | Values | Description |  |
| :---: | :---: | :---: | :---: |
| Object type | Switching (1 bit) <br> Priority (2 bit) <br> Value 0-255 <br> Percentage value (1 byte) <br> Height \% + slat \% | Telegram type for this object. |  |
| Telegram | With object type $=$ switching 1 bit |  |  |
|  | $\begin{aligned} & \text { ON } \\ & \text { OFF } \\ & \text { INVERT } \end{aligned}$ | Send switch-on command Send switch-off command Invert current state (ON-OFF-ON etc.) |  |
|  | With object type = priority 2 bit |  |  |
|  |  | Function | Value |
|  | inactive | Priority inactive (no control) | 0 ( $00{ }_{\text {bin }}$ ) |
|  | ON | Priority ON (control: enable, on) | 3 (11 ${ }_{\text {bin }}$ ) |
|  | OFF | Priority OFF (control: disable, off) | 2 (10 bin $)$ |
|  | With object type = value 0-255 |  |  |
|  | 0-255 | Any value between 0 and 255 can be sent. |  |
|  | With object type = percentage value <br> 1 byte |  |  |
|  | 0-100\% | Any percentage value between 0 and $100 \%$ can be sent. |  |
|  | $\begin{aligned} & \text { With object type = height \% } \\ & + \text { slat \% } \end{aligned}$ |  |  |
|  | Height | Upon double-click 2 telegrams are sent simultaneously: Required blind height |  |
|  | Slat | Required slat position. |  |
| Send cyclically | do not send cyclically every min every 2 min every 3 min ... every 45 min every 60 min | How often should it be resent? |  |
| Response after restoration of the bus supply ${ }^{48}$ | none <br> As with double-click (immediately) <br> As with double-click (after 5 s) <br> As with double-click (after 10 s) <br> As with double-click (after 15 s) | Do not send. <br> Send update telegram immediately or with delay. The value to be sent depends on the value configured for doubleclick. |  |

[^12]$\left.$| Designation | Values | Description |
| :--- | :--- | :--- |
| Response when the <br> block is set | Ignore block | The block function is ineffective <br> with this telegram. |
|  | no response | Do not respond when the block is <br> set. |
| as with double-click |  |  |$\quad$| Respond as with a double-click. |
| :--- | \right\rvert\, | Ro not respond when the block is |
| :--- |
| cancelled. |
| block is cancelled |$\quad$| Respond as with a double-click. |
| :--- |

### 6.8.4.2 Blinds parameter page

| Designation | Values | Description |
| :---: | :---: | :---: |
| Operation | One button operation <br> DOWN <br> UP | The input distinguishes between a long and a short button push, and can thus carry out 2 functions. <br> The blinds are operated with a single button. <br> Short button push = step. <br> Long button push = move. <br> Short button push = step. <br> Long button push = lower. <br> Short button push = step. <br> Long button push = raise. |
| Movement is stopped by | Releasing the button Short operation | How is the stop command to be triggered? |
| Response after restoration of the mains or bus supply | none <br> UP <br> DOWN <br> UP after 5 s <br> UP after 10 s <br> UP after 15 s <br> DOWN after 5 s DOWN after 10 s <br> DOWN after 15 s | Do not respond. <br> Raise blinds <br> Lower blinds <br> Raise blinds with delay <br> Lower blinds with delay |
| Response when the block is set | Ignore block <br> no response <br> UP <br> DOWN | The block function is ineffective with this telegram. <br> Do not respond when the block is set. <br> Raise blinds <br> Lower blinds |
| Response when the block is cancelled | no response <br> ON <br> OFF | Do not respond when the block is cancelled. <br> Raise blinds <br> Lower blinds |

## theben

### 6.8.5 Input I2: Temperature input ${ }^{49}$

| Designation | Values | Description |
| :---: | :---: | :---: |
| Channel function | Switch.. <br> Button.. <br> Dimming.. <br> Blinds.. <br> Temperature input ${ }^{50}$ | The input is connected to a temperature sensor. |
| Sensor type | Remote sensor 1 (9070191) <br> Remote sensor IP 65 (9070459) <br> Floor sensor (9070321) | External temperature sensor 1 Item no. 9070191, for surface-mounted installation. <br> External temperature sensor RAMSES IP65 Item no. 9070459, for surface-mounted installation. <br> Temperature sensor for laying in floor, IP65 protection rating. |
| Temperature calibration | $\begin{aligned} & -64 .+64 \\ & (\times 0.1 \mathrm{~K}) \end{aligned}$ | Correction value for temperature measurement if sent temperature deviates from the actual ambient temperature. <br> Example: Temperature $=20^{\circ} \mathrm{C}$ <br> sent temperature $=21^{\circ} \mathrm{C}$ <br> Correction value $=10$ <br> (d.h. $10 \times 0.1^{\circ} \mathrm{C}$ ) |
| Transmit temperature in the event of change of | not due to a change $\begin{aligned} & 0.2 \mathrm{~K} \\ & 0.3 \mathrm{~K} \\ & 0.5 \mathrm{~K} \\ & 0.7 \mathrm{~K} \\ & 1 \mathrm{~K} \\ & 1.5 \mathrm{~K} \\ & 2 \mathrm{~K} \\ & \hline \end{aligned}$ | Only send cyclically (if enabled) <br> Send if the value has changed by the selected amount since the last transmission. |
| Send temperature cyclically | do not send cyclically every min, every 2 min. every 3 min. <br> every 45 min. <br> every 60 min . | How often should the current measured value be resent? |

[^13]
### 6.8.6 Input 11, I2: window contact function

(i) The window contact function is only available in connection with C 1 as blind actuator

| Designation | Values | Description |
| :---: | :---: | :---: |
| Function | Switch.. ${ }^{51}$ <br> Button.. ${ }^{52}$ <br> Dimming.. <br> Blinds.. ${ }^{53}$ <br> Window contact.. | Desired use. |
| Control channel C1 directly | No | I1 is used purely as a KNX binary input. <br> There is no internal connection to the blind actuator. |
| Debounce time | $30 \mathrm{~ms}, 50 \mathrm{~ms}, 80 \mathrm{~ms}$ $100 \mathrm{~ms}, 200 \mathrm{~ms}$, $1 \mathrm{~s}, 5 \mathrm{~s}, 10 \mathrm{~s}$ | In order to avoid disruptive switching due to bouncing of the contact connected to the input, the new status of the input is only accepted after a delay time. Larger values ( $\geq 1 \mathrm{~s}$ ) can be used as a switch-on delay |
| Send cyclically | every min every 2 min every 3 min every 30 min every 45 min every 60 min | Common cycle time for all 3 output objects of the channel. |
| Activate block function | по <br> yes | No block function. <br> Show parameters for the block function. |
| Block telegram | Block with 1 (standard) <br> Block with 0 | $\begin{aligned} & 0=\text { cancel block } \\ & 1=\text { block } \\ & 0=\text { block } \\ & 1=\text { cancel block } \end{aligned}$ |

${ }^{51}$ Direct control of C1 possible (switch actuator).
${ }^{52}$ Direct control of C1 possible (switch actuator).
${ }^{53}$ Direct control of C1 possible (blind actuator).
The output objects channel 11 - window contact 1 and channel 12 - window
contact 2 are not connected to blind actuator channel $C 1$ internally.
The connection is exclusively implemented via bus telegrams. ${ }^{54}$
For this purpose, these objects are connected with the objects
channel $C 1$ - window contact 1,2 of the actuator via group addresses.

[^14]
## theben

6.8.6.1 Window contact

| Designation | Values | Description |
| :---: | :---: | :---: |
| Telegram when contact closed | $\begin{array}{\|l\|} \hline \text { On } \\ \text { Off } \\ \hline \end{array}$ | Set switching status. |
| Telegram when contact open | $\begin{array}{\|l\|} \hline \text { On } \\ \text { Off } \\ \hline \end{array}$ | Is set automatically. |
| Send cyclically | по yes, always only if input $=1$ only if input $=0$ | When should cyclical sending take place? <br> The cycle time is set on the main parameter page of the channel. |
| Response after restoration of the bus supply ${ }^{55}$ | none <br> update (immediately) update (after 5 s) update (after 10 s ) update (after 15 s ) | Do not send. <br> Send update telegram immediately or with delay. |
| Response when the block is set | Ignore block <br> no response <br> as with input $=1$ <br> as with input $=0$ | The block function is ineffective with this telegram. <br> Do not respond when the block is set. <br> Respond as with rising edge. <br> Respond as with falling edge. |
| Response when the block is cancelled | no response update | Do not respond when the block is cancelled. <br> Send update telegram. |

### 6.9 Parameters for direct control of the blind actuator

## (i)

The parameter Control channel C1 (C2) directly determines whether the input functions as a direct control for C1 or purely as a KNX binary input.
Channels I1 and I2 are configured for direct control of the actuator in the ETS default setting.
A button connected to 11 will therefore have a direct internal effect on channel C1, a button or switch at I2 affects C2.
(1) If the operation of the blinds requires 2 buttons (operation up/down), i.e. 2 inputs, then 12 will be automatically configured for direct control.
(1) If the operation of the blinds requires only one button (one button operation), then input 12 is freely available as a KNX binary input.

If an input is configured for direct control, it has no bus connection, i.e. no communication objects.

### 6.9.1 I1 blind actuator directly: Configuration options

| Designation | Values | Description |
| :--- | :--- | :--- |
| Channel function | Switch.. <br> Button.. <br> Dimming.. <br> Blinds.. <br> Window contact | A direct control of the blind <br> actuator (C1) is only possible <br> with the blinds function. |
| Control channel C1 directly ${ }^{56}$ | yes | I1 is used exclusively as a <br> button input for blind actuator <br> channel C1. <br> I1 is connected to C1 internally <br> and has no communication <br> objects. <br> I2 will be integrated <br> automatically, if required. |
| Input is used purely as a KNX |  |  |
| binary input. |  |  |
| There is no internal connection to |  |  |
| the switch actuator. |  |  |

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## theben

| Designation | Values | Description |
| :---: | :---: | :---: |
| Debounce time ${ }^{57}$ | $30 \mathrm{~ms}, 50 \mathrm{~ms}, 80 \mathrm{~ms}$ $100 \mathrm{~ms}, 200 \mathrm{~ms}$, $1 \mathrm{~s}, 5 \mathrm{~s}, 10 \mathrm{~s}$ | In order to avoid disruptive switching due to bouncing of the contact connected to the input, the new status of the input is only accepted after a delay time. Larger values ( $\geq 1 \mathrm{~s}$ ) can be used as a switch-on delay |
| Long button push starting at ${ }^{58}$ | $\begin{aligned} & 300 \mathrm{~ms}, 400 \mathrm{~ms} \\ & 500 \mathrm{~ms}, 600 \mathrm{~ms} \\ & 700 \mathrm{~ms}, 800 \mathrm{~ms} \\ & 900 \mathrm{~ms}, 1 \mathrm{~s} \end{aligned}$ | Serves to clearly differentiate between long and short button push. <br> If the button is pressed for at least as long as the set time, then a long button push will be registered. |
| Double-click additional function | по <br> yes | No double-click function <br> The double-click parameter page is shown. |
| Time for double-click ${ }^{59}$ | $\begin{aligned} & 300 \mathrm{~ms}, 400 \mathrm{~ms} \\ & 500 \mathrm{~ms}, 600 \mathrm{~ms} \\ & 700 \mathrm{~ms}, 800 \mathrm{~ms} \\ & 900 \mathrm{~ms}, 1 \mathrm{~s} \end{aligned}$ | Serves to differentiate between a double-click and 2 single clicks. Time period in which the second click must begin, in order to recognise a double-click. |

[^16]
## theben

### 6.9.1.1 I1 blinds directly parameter page

| Designation | Values | Description |
| :---: | :---: | :---: |
| Operation |  | The input distinguishes between a long and a short button push, and can thus carry out 2 functions. |
|  | One button operation | The blinds are operated with a single button. <br> Short button push = step. <br> Long button push = move. |
|  |  | (i) <br> 12 is not required, and freely available |
|  | DOWN | Short button push = step. <br> Long button push = lower. |
|  |  | (i) 12 is automatically preallocated with operation $=U P$. |
|  | UP | Short button push = step. Long button push = raise. |
|  |  | (i) <br> 12 is automatically preallocated with operation $=$ DOWN. |
| Movement is stopped by | Releasing the button Short operation | How is the stop command to be triggered? |

### 6.9.1.2 Double-click parameter page

| Designation | Values | Description |
| :--- | :--- | :--- |
| Height | $0-100 \%$ | Required blind height |
| Slat | $0-100 \%$ | Required slat position. |

### 6.9.2 12 blinds directly

This parameter page is shown if 12 is required for direct control.
This is the case if, on the Blinds input 11 directly parameter page, the parameter Operation is set to UP or DOWN, and therefore a second button is required for the opposite direction
(i) If the blinds are operated with only one button (one button operation), then input I2 is freely available as a KNX binary input.

| Designation | Values | Description |
| :--- | :--- | :--- |
| Operation | DOWN | Presetting if the direction is set <br> to UP at IT. <br> Presetting if the direction is set <br> to DOWN at IT. |
| Double-click additional function | no | No double-click function <br> The double-click parameter page <br> is shown. |
| Height | yes | Required blind height |
| Slat | $0-100 \%$ | Required slat position. |

(i) The following settings are taken over from I1, and do not have to be entered again at I2: debounce time, long button push from, time for double-click.

### 6.10 Parameters for direct control of the switch actuator

The parameter Control channel C1 (C2) directly determines whether the input functions as a direct control for C1 (C2) or purely as a KNX binary input. Channels I1 and I2 are configured for direct control of the actuator in the ETS default setting.

A button or switch connected to 11 will therefore have a direct internal effect on channel C1, a button or switch at I2 affects C2.
 communication objects.

### 6.10.1 Control switch actuator directly, switch function

| Designation | Values | Description |
| :--- | :--- | :--- |
| Function | Switch.. <br> Button.. <br> Dimmming... <br> Blinds... | Direct control of the switch <br> actuator (C1/C2) is only possible <br> with the switch or button <br> functions. |
| Control channel C1 directly ${ }^{60}$ | yes | Input is used exclusively for <br> switch actuator channel C1 (or <br> C2). <br> I1 is connected to C1 internally <br> (or I2 to C2) and has no <br> communication objects. |
| Debounce time | No | Input is used purely as a KNX <br> binary input. <br> There is no internal connection to <br> the switch actuator. |
|  | $100 \mathrm{~ms}, 50 \mathrm{~ms}, 200 \mathrm{~ms}$, <br> $1 \mathrm{~ms} 5 \mathrm{~s}, 10 \mathrm{~s}$ | In order to avoid disruptive <br> switching due to bouncing of the <br> contact connected to the input, <br> the new status of the input is <br> only accepted after a delay time. <br> Larger values ( $\geq 1 \mathrm{~s}$ ) can be used <br> as a switch-on delay. |

[^17]
### 6.10.1.1 Direct switching parameter page

This page replaces the switch object 1, 2 parameter pages.

| Designation | Values | Description |
| :--- | :--- | :--- |
| Switching status if <br> input = 1 | On <br> Off <br> Change over | Switching status if voltage is <br> present at the input? |
| Switching status if <br> input = 0 | on <br> off <br> Change over | Switching status if no voltage is <br> present at the input? |

6.10.2 Control switch actuator directly, button function

| Designation | Values | Description |
| :---: | :---: | :---: |
| Function | Switch.. <br> Button.. <br> Dimming... <br> Blinds.. | Direct control of the switch actuator (C1/C2) is only possible with the switch or button functions. |
| Control channel C1 directly ${ }^{61}$ | yes <br> No | Input is used exclusively for switch actuator channel C1 (or C2). <br> I1 is connected to C1 internally (or I2 to C2) and has no communication objects. <br> Input is used purely as a KNX binary input. <br> There is no internal connection to the switch actuator. |
| Debounce time | $30 \mathrm{~ms}, 50 \mathrm{~ms}, 80 \mathrm{~ms}$ <br> $100 \mathrm{~ms}, 200 \mathrm{~ms}$, <br> $1 \mathrm{~s}, 5 \mathrm{~s}, 10 \mathrm{~s}$ | In order to avoid disruptive switching due to bouncing of the contact connected to the input, the new status of the input is only accepted after a delay time. Larger values ( $\geq 1 \mathrm{~s}$ ) can be used as a switch-on delay |
| Connected button | NO contact NC contact | Set the type of connected contact. |
| Long button push starting at | $\begin{aligned} & 300 \mathrm{~ms}, 400 \mathrm{~ms} \\ & 500 \mathrm{~ms}, 600 \mathrm{~ms} \\ & 700 \mathrm{~ms}, 800 \mathrm{~ms} \\ & 900 \mathrm{~ms}, 1 \mathrm{~s} \end{aligned}$ | Serves to clearly differentiate between long and short button push. <br> If the button is pressed for at least as long as the set time, then a long button push will be registered. |
| Time for double-click | $\begin{aligned} & 300 \mathrm{~ms}, 400 \mathrm{~ms} \\ & 500 \mathrm{~ms}, 600 \mathrm{~ms} \\ & 700 \mathrm{~ms}, 800 \mathrm{~ms} \\ & 900 \mathrm{~ms}, 1 \mathrm{~s} \end{aligned}$ | Serves to differentiate between a double-click and 2 single clicks. Time period in which the second click must begin, in order to recognise a double-click. |

${ }^{61}$ Direct control: This parameter is only available for the switch or button function.

### 6.10.2.1 Direct switching parameter page

This page replaces the switch object 1, 2 parameter pages.

| Designation | Values | Description |
| :--- | :--- | :--- |
| Response after short <br> operation | No response <br> Switching | Execute a switch command after <br> a short button push? |
| Switching status | On <br> Off <br> Change over | Switching status. |
| Response after long <br> operation | No response <br> Switching | Execute a switch command after <br> a long button push? |
| Switching status | Off <br> Change over | Switching status. <br> Response after double- <br> click |
| No response <br> Switching | Execute a switch command after <br> a double-click? |  |

## 7 Application examples - blind actuator

### 7.1 Blind actuator direct control: Basic configuration

In this configuration, the blind actuator is operated directly with the buttons connected to 11 and 12.

### 7.1.1 Devices

- JU 1 (4942550)


### 7.1.2 Overview



### 7.1.3 Objects and links

The communication objects of C1 are all available for further functions.
A basic function (blinds up/down, step/stop) is provided via actuation of inputs I1 and I2.
In this case, the external inputs 11 and I 2 have no communication objects.

### 7.1.4 Important parameter settings

Standard or customer-defined parameter settings apply for unlisted parameters.

JU 1:

| Parameter page | Parameter | Setting |
| :--- | :--- | :--- |
| General | Usage | 1-channel blind actuator |
|  | Use binary inputs | Yes |
| External inputs |  |  |
| 11, I2 configuration options | Function | Blinds |
|  | Control channel C1 directly | yes |
| Blinds directly I1 | Operation | Up |
| Blinds directly I2 | Operation | Down ${ }^{62}$ |

${ }^{62}$ Not adjustable, will be adjusted automatically.

### 7.2 Controlling the blind actuator via the bus

In this example, the external inputs and the blind actuator channel are completely separate from each other and can only be used via the KNX bus. ${ }^{63}$

The blind actuator channel of the JU 1 is operated by means of a KNX button interface (TA 2 S). The automatic sun function is implemented by the Meteodata 140 S weather station.
In case of a wind alarm, the drive will be moved up.
The external inputs I1, I2 control a further KNX switch actuator (RM 4 U ).

### 7.2.1 Devices

- JU 1 (4942550)
- TA 2 S (4969222)
- RM4U(4940223)
- Meteodata 140 S weather station (1409207)


### 7.2.2 Overview



[^18]
## theben

### 7.2.3 Objects and links

| No. | JU 1 | No. | RM 4 U | Comment |
| :--- | :--- | :--- | :--- | :--- |
|  | Object name |  | The external inputs control switch |  |
| 41 | Channel I1.1 - <br> switching | 0 | Channel C1 - switch <br> object | actuator RM 4 U |


| No. | TA 2 S | No. | JU 1 | Comment |
| :---: | :---: | :---: | :---: | :---: |
|  | Object name |  | Object name |  |
| 1 | Channel 11 step / stop | 2 | Channel C1 - | The step telegrams from both buttons of the button interface are sent to the same group address. |
| 11 | Channel 12 step / stop |  | step / <br> stop |  |
| 2 | $\begin{aligned} & \text { Channel l1 - } \\ & \text { up } \end{aligned}$ | 1 | Up / down | The up and down telegrams of the button interface are sent to the same group address. . |
| 12 | Channel 12 down |  |  |  |


| No. | Meteodata 140 S |  | No. | JU |
| :---: | :--- | :--- | :--- | :--- |
|  | Object name |  |  |  |
| 20 | C1.1 Universal channel <br> - <br> Switching | 75 | Central safety - wind <br> 1 | Wind alarm |
| 60 | C11 Drives up/down | 1 | Up / down | Controlled by automatic sun |
| 61 | C11 Blinds height | 3 | $\%$ height |  |
| 62 | C11 Slat position | 4 | $\%$ slat |  |

## theben

### 7.2.4 Important parameter settings

Standard or customer-defined parameter settings apply for unlisted parameters.

JU 1:

| Parameter page | Parameter | Setting |
| :--- | :--- | :--- |
| General | Usage | 1-channel blind <br> actuator |
|  | Use binary inputs | Yes |
|  | Type of hanging | Blinds |
| Safety wind / rain / frost | Participation in safety wind | yes |
|  | Source | Safety object 1 <br> wind |
|  | Start | Top end position |
| External inputs |  |  |
| 11, I2 configuration options | Function | Button |
|  | Control channel C1, C2 directly | no |
| Button object 2 | Object type | Switching |
|  | Telegram | Change over |
|  | Object type | Switching |
|  | Telegram | Change over |

RM 4 U:

| Parameter page | Parameter | Setting |
| :--- | :--- | :--- |
| Configuration options | Channel function | Switch on/off |
|  | Activation of function via | Switch object |

TA 2 S :

| Parameter page | Parameter | Setting |
| :--- | :--- | :--- |
| Channel 1 configuration options | Channel 1 function | Blinds |
| Blinds | Operation | Up |
| Channel 2 configuration options | Channel 2 function | Blinds |
| Blinds | Operation | Down |

## theben

Meteodata 140 S:

| Parameter page | Parameter | Setting |
| :--- | :--- | :--- |
| General | Activate universal channel C1 | Yes |
|  | Activate sun protection channel C11 | Yes |
|  | Channel function | Wind sensor |
| Objects | Wind speed | Above $4 \mathrm{~m} / \mathrm{s}^{64}$ |
|  | Telegram type C1.1 | Switch command |
|  | If the condition is met | Send cyclically |
|  | Telegram | On |
|  | If the condition is not met | Send cyclically |
|  | Telegram | Off |
| C11 protection channel | Channel controls | Blinds |
| Automatic sun function | Activation of automatic sun function | Via dimming threshold |

### 7.3 Blind actuator with ventilation function



The ventilation function moves the blinds or overrule the blinds automatically into a predefined position ${ }^{65}$, as soon as the window is tilted or opened.

In order to distinguish between tilted and open, the window must be equipped with 2 contacts. The combined switching status of both contacts (at I1 and I2) enables the detection of the current window setting.

Here, the following configuration is assumed:

|  | Window contact 1 |  | Window contact 2 |  |
| :--- | :---: | :---: | :---: | :---: |
|  | Status ${ }^{66}$ | Telegram $^{67}$ | Status ${ }^{68}$ | Telegram $^{69}$ |
| Window tilted | open | Off | closed | On |
| Window open | closed | On | closed | On |

Inputs 11 and I 2 send the status of the window contacts via the bus to the objects window contact 1 and 2 of blind actuator C1.

The blind actuator is operated by means of a KNX button interface (TA 2 S ).

### 7.3.1 Devices

- JU 1 (4942550)
- TA 2 S (4969222)


### 7.3.2 Overview



[^19]
### 7.3.3 Objects and links

| No. | JU 1 | No. | JU 1 | Comment |
| :---: | :---: | :---: | :---: | :---: |
|  | Object name |  | Object name |  |
| 41 | Channel 11.1 switching | 24 | Channel C1 window contact 1 | 11 is connected with the first window contact object of the blind actuator via an own group address. |
| 51 | Channel 12.1 switching | 25 | Channel C1 window contact 2 | 12 is connected with the second window contact object of the blind actuator via an own group address. |


| No. | TA 2 S | No. | JU 1 | Comment |
| :---: | :---: | :---: | :---: | :---: |
|  | Object name |  | Object name |  |
| 1 | Channel 11 step / stop | 2 | Channel C1 step / stop | The step telegrams from both buttons of the button interface are sent to the same group address. . |
| 11 | Channel 12 step / stop |  |  |  |
| 2 | $\begin{aligned} & \text { Channel I1 } \\ & \text { - up } \end{aligned}$ | 1 | Up / down | The up and down telegrams of the button interface are sent to the same group address. . |
| 12 | Channel 12 <br> - down |  |  |  |

### 7.3.4 Important parameter settings

Standard or customer-defined parameter settings apply for unlisted parameters.

JU 1:

| Parameter page | Parameter | Setting |
| :---: | :---: | :---: |
| General | Usage | 1-channel blind actuator |
|  | Use binary inputs | Yes |
| C1 configuration options | Type of hanging | Blinds |
|  | Activate ventilation function | Yes |
| Ventilation ${ }^{70}$ | When the window is tilted |  |
|  | Approach ventilation position | always |
|  | Position | Preset 1 |
|  | When the window is open |  |
|  | Approach ventilation position | always |
|  | Position | Preset 2 |
|  | When the window is closed |  |
|  | Position after end of ventilation | As before ventilation |
| Presets ${ }^{71}$ | Preset 1 |  |
|  | Height | 0\% |
|  | Slat | 0\% |
|  | Preset 2 |  |
|  | Height | 80\% |
|  | Slat | 0\% |
| Window contacts | Number of window contents for this window | 2 contacts |
|  | When the window is tilted |  |
|  | Status of object window contact 1 | Off |
|  | Status of object window contact 2 | On |
|  | When the window is open |  |
|  | Status of object window contact 1 | On |
|  | Status of object window contact 2 | On |
| External inputs |  |  |
| Configuration options 11, 12 | Function | Window contact |
|  | Control channel C1, C2 directly | по |
| Window contact 11 | Telegram when contact closed | On |
|  | Telegram when contact open | Off72 |
| Window contact 12 | Telegram when contact closed | On |
|  | Telegram when contact open | Off73 |

70 These settings are user-specific. Here, values are only given as an example.
${ }^{71}$ These settings are user-specific. Here, values are only given as an example.
${ }^{72}$ Not adjustable, will be adjusted automatically.
${ }^{73}$ Not adjustable, will be adjusted automatically.

TA 2 S :

| Parameter page | Parameter | Setting |
| :--- | :--- | :--- |
| Channel 1 configuration options | Channel 1 function | Blinds |
| Blinds | Operation | Up |
| Channel 2 configuration options | Channel 2 function | Blinds |
| Blinds | Operation | Down |

## 8 Application examples - switch actuator

These application examples are designed to aid planning and are not to be considered an exhaustive list.
They can be extended and updated as required.

### 8.1 Direct control of switch actuator: Basic configuration

In this configuration, both switching channels are operated directly with buttons ${ }^{74}$ connected to 11 and 12.
Each time the button is pressed, the corresponding channel-relay is switched.

### 8.1.1 Devices

- JU 1 (4942550)


### 8.1.2 Overview



### 8.1.3 Objects and links

The communication objects of C1 and C2 are all available for further functions. A basic function (C1, C2 On/Off) is provided via actuation of inputs I 1 and I 2 .

In this case, the external inputs I 1 and I 2 have no communication objects.

[^20]
### 8.1.4 Important parameter settings

Standard or customer-defined parameter settings apply for unlisted parameters.

JU 1:

| Parameter page | Parameter | Setting |
| :--- | :--- | :--- |
| General | Usage | 2-channel switch actuator |
|  | Use binary inputs | Yes |
| Configuration options C1,C2 | 点 | Channel function |
| External inputs | Switch on/off76 |  |
| 11, I2 configuration options | Function | Button ${ }^{77}$ |
|  | Control channel C1 directly | yes |
| Direct switching | Response after short operation | Switching |
|  | Switching status | Change over |

[^21]
### 8.2 Controlling switch actuator channels via the bus

In this example, the external inputs and the switch actuator channels are completely separate from each other and can only be used via the KNX bus. ${ }^{78}$

The switch actuator channels of the JU 1 are operated by means of a KNX button interface (TA 2 S).
The external inputs I1, I2 control a further KNX switch actuator (RM 4 U ).

### 8.2.1 Devices

- JU 1 (4942550)
- TA 2 S (4969222)
- RM 4 U (4940223)


### 8.2.2 Overview



[^22]
### 8.2.3 Objects and links

| No. | JU 1 | No. | RM 4 U | Comment |
| :--- | :--- | :--- | :--- | :--- |
|  | Object name |  |  |  |
| 41 | Channel I1.1 - <br> switching | 0 | Channel C1 - switch <br> object | The external inputs control switch <br> actuator RM 4 U |
| 51 | Channel I2.1 - <br> switching | 10 | Channel C2 - switch <br> object |  |


| No. | TA 2 S | No. | JU 1 | Comment |
| :--- | :--- | :--- | :--- | :--- |
|  | Object name |  | Object name |  |
| 1 | Channel I1.1 - <br> switching | 1 | Channel C1 - <br> switch object | The button interface controls the |
| 11 | Channel I2.1 - <br> switching | 21 | Channel C2 - <br> switch object | switching channels C1 and C2. |

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### 8.2.4 Important parameter settings

Standard or customer-defined parameter settings apply for unlisted parameters.

JU 1:

| Parameter page | Parameter | Setting |
| :--- | :--- | :--- |
| General | Usage | 2-channel switch <br> actuator |
|  | Use binary inputs | Yes |
|  | Channel function | any |
| External inputs |  |  |
| 11, I2 configuration options | Function | Button |
|  | Control channel C1, C2 directly | no |
| Button object 1 | Object type | Switching |
|  | Telegram | Change over |
| Button object 2 | Object type | Switching |
|  | Telegram | Change over |

RM 4 U:

| Parameter page | Parameter | Setting |
| :--- | :--- | :--- |
| Configuration options C1, C2 | Channel function | Switch on/off |
|  | Activation of function via | Switch object |

TA 2 S :

| Parameter page | Parameter | Setting |
| :--- | :--- | :--- |
| Channel 1 configuration options | Channel 1 function | Button |
| Button object 1 | Object type | Switching (1 bit) |
|  | Send after short operation | Send telegram |
|  | Value | Change over |
| Channel 2 configuration options | Channel 2 function | Button |
| Button object 1 | Object type | Switching (1 bit) |
|  | Send after short operation | Send telegram |
|  | Value | Change over |

### 8.3 Switch actuator channels with and without direct control

In this example, bus and direct control are flexibly combined with each other:

- $\quad 11$ is configured as a pure KNX binary input, and it controls a dimming actuator.
- $\quad 12$ is connected directly with C2 internally.
- $\quad \mathrm{C} 1$ is exclusively controlled via the bus.
- C2 can be operated directly via a button at I2, as well as via bus telegrams, at the same time.

Both switch actuator channels of the JU 1 are operated by means of a KNX button interface (TA 2 S).

### 8.3.1 Devices

- JU 1 (4942550)
- TA 2 S (4969222)
- DM 2 T(4940270)


### 8.3.2 Overview



### 8.3.3 Objects and links

| No. | JU 1 |  | DM 2 T | Comment |
| :--- | :--- | :--- | :--- | :--- |
|  | Object name |  | The external input I1 controls the |  |
| 41 | Channel I1 - <br> switching | 0 | Channel C1 - switching <br> On/Off | dimming actuator DM 2 T. |
| 42 | Channel I1 - <br> brighter / <br> darker | 1 | Channel C1 - <br> brighter/darker |  |


| No. | TA 2 S | No. | JU 1 | Comment |
| :--- | :--- | :--- | :--- | :--- |
|  | Object name |  | Object name |  |
| 1 | Channel I1.1 - <br> switching | 1 | Channel C1 - <br> switch object | The first channel of button interface TA 2 S <br> is controlled by C1. |
| 11 | Channel I2.1- <br> switching | 21 | Channel C2 - <br> switch object | The second channel of button interface TA 2 S <br> is controlled by C2. <br> Independently, C2 can also be operated with <br> the button at the external input I2 of the JU 1. |

## theben

### 8.3.4 Important parameter settings

Standard or customer-defined parameter settings apply for unlisted parameters.

JU 1:

| Parameter page | Parameter | Setting |
| :--- | :--- | :--- |
| General | Usage | 2-channel switch actuator |
|  | Use binary inputs | Yes |
|  | Channel function | any |
| External inputs |  |  |
| 11 configuration options | Function | Dimming |
|  | Control channel C1 directly | no |
| Dimming | Response to long/short | One button operation |
| I2 configuration options | Function | Button |
|  | Control channel C2 directly | yes |
| Direct switching79 | Response after short operation | Switching |
|  | Switching status | Change over |

TA 2 S:

| Parameter page | Parameter | Setting |
| :--- | :--- | :--- |
| Channel 1 configuration options | Channel 1 function | Button |
| Button object 1 | Object type | Switching (1 bit) |
|  | Send after short operation | Send telegram |
|  | Value | Change over |
| Channel 2 configuration options | Channel 2 function | Button |
| Button object 1 | Object type | Switching (1 bit) |
|  | Send after short operation | Send telegram |
|  | Value | Change over |

## DM 2 T:

No specific configuration required.
This device can be configured with the standard or customer-defined parameter settings.

## 9 Appendix

### 9.1 General information about KNX RF

As with KNX TP, KNX RF also distinguishes between Standard and Easy mode.
The standard mode is called "KNX RF1.R S mode". The carrier frequency is 868.3 MHz . This relatively low frequency offers excellent signal propagation compared to higher frequencies (Bluetooth: 2.4 GHz or WLAN: $2.4 / 5 \mathrm{GHz}$ ) and a good balance between power consumption and range. The range in the free field is up to 100 m . Inside buildings, the range depends on structural factors and conditions.
The structural conditions and distances between the radio products must already be taken into account when planning the electrical installation. The radio signals are mainly dampened by e.g. concrete components with steel reinforcement or metal components. The more dampening components between transmitter and receiver and the greater the distance, the more critical for the radio communication. For a system with TP and RF lines, the placement of the media coupler must be planned as much in the center as possible.
Furthermore, the frequency range used by KNX RF is not exclusively available to KNX. This means other radio systems might also be in a building and influence the KNX RF communication (e.g. garage door drives, alarm systems, weather stations, etc.).

Other devices, such as ballasts and lamps, can also be potential sources of interference for KNX RF systems due to the emission of electromagnetic waves.
The ETS app KNX RF Field Strength Analyzer from Tapko Technologies GmbH shows the receiving field strength of selected KNX RF products and can support start-up and troubleshooting.

In ETS 5, the "RF" transmission medium can be selected for a line. The KNX RF products are included in this line. For each line with "RF" medium, the ETS generates a unique domain address. The KNX RF products added in the RF line are assigned to this domain address. This ensures that pieces of information from neighbouring KNX RF lines will not influence each other. Only devices with the same domain address communicate with each other. The domain address is automatically transmitted by the ETS when programming the KNX RF products. An RF line can have a maximum of 256 devices (addresses 0...255). If the system consists of several RF lines or a combination of TP and RF media, the first device in the RF line is always a media coupler with the physical address x.x. 0 (e.g. 1.2.0). The media coupler transmits the information across lines via the TP medium. KNX RF products are easy to recognise in the ETS product catalogue due to the specific radio symbol.

### 9.2 The scenes

### 9.2.1 Principle

The current status of a channel, or of a complete device, can be stored and retrieved later at any time via the scene function.

Each channel can participate simultaneously in up to 8 scenes.
Scene numbers 1 to 64 are permitted.
Permission to participate in scenes must be granted for the relevant channel via parameter. See Activate scenes parameter and Scenes parameter page.

The current status is allocated to the appropriate scene number when a scene is saved.
The previously saved status is restored when a scene number is called up.
This allows a device to be easily integrated into any chosen user scene.
The scenes are permanently stored and remain intact even after the application has been downloaded again.
See "All channel scene statuses" parameter on the Scenes parameter page.

## theben

### 9.2.2 Calling up or saving scenes:

To call up or save a scene, the relevant code is sent to the corresponding scene object.

| Scenario | Call up |  | Save |  |
| :---: | :---: | :---: | :---: | :---: |
|  | Hex. | Dec. | Hex. | Dec. |
| 1 | \$00 | 0 | \$80 | 128 |
| 2 | \$01 | 1 | \$81 | 129 |
| 3 | \$02 | 2 | \$82 | 130 |
| 4 | \$03 | 3 | \$83 | 131 |
| 5 | \$04 | 4 | \$84 | 132 |
| 6 | \$05 | 5 | \$85 | 133 |
| 7 | \$06 | 6 | \$86 | 134 |
| 8 | \$07 | 7 | \$87 | 135 |
| 9 | \$08 | 8 | \$88 | 136 |
| 10 | \$09 | 9 | \$89 | 137 |
| 11 | \$0A | 10 | \$8A | 138 |
| 12 | \$0B | 11 | \$8B | 139 |
| 13 | \$0C | 12 | \$8C | 140 |
| 14 | \$0D | 13 | \$8D | 141 |
| 15 | \$0E | 14 | \$8E | 142 |
| 16 | \$0F | 15 | \$8F | 143 |
| 17 | \$10 | 16 | \$90 | 144 |
| 18 | \$11 | 17 | \$91 | 145 |
| 19 | \$12 | 18 | \$92 | 146 |
| 20 | \$13 | 19 | \$93 | 147 |
| 21 | \$14 | 20 | \$94 | 148 |
| 22 | \$15 | 21 | \$95 | 149 |
| 23 | \$16 | 22 | \$96 | 150 |
| 24 | \$17 | 23 | \$97 | 151 |
| 25 | \$18 | 24 | \$98 | 152 |
| 26 | \$19 | 25 | \$99 | 153 |
| 27 | \$1A | 26 | \$9A | 154 |
| 28 | \$1B | 27 | \$9B | 155 |
| 29 | \$1C | 28 | \$9C | 156 |
| 30 | \$1D | 29 | \$9D | 157 |
| 31 | \$1E | 30 | \$9E | 158 |
| 32 | \$1F | 31 | \$9F | 159 |
| 33 | \$20 | 32 | \$AO | 160 |
| 34 | \$21 | 33 | \$A1 | 161 |
| 35 | \$22 | 34 | \$A2 | 162 |
| 36 | \$23 | 35 | \$A3 | 163 |
| 37 | \$24 | 36 | \$A4 | 164 |
| 38 | \$25 | 37 | \$A5 | 165 |
| 39 | \$26 | 38 | \$A6 | 166 |
| 40 | \$27 | 39 | \$A7 | 167 |
| 41 | \$28 | 40 | \$A8 | 168 |
| 42 | \$29 | 41 | \$A9 | 169 |
| 43 | \$2A | 42 | \$AA | 170 |
| 44 | \$2B | 43 | \$AB | 171 |
| 45 | \$2C | 44 | \$AC | 172 |
| 46 | \$2D | 45 | \$AD | 173 |
| 47 | \$2E | 46 | \$AE | 174 |


| Scenario | Call up |  | Save |  |
| :---: | :---: | :---: | :---: | :---: |
|  | Hex. | Dec. | Hex. | Dec. |
| 48 | $\$ 2 F$ | 47 | $\$ A F$ | 175 |
| 49 | $\$ 30$ | 48 | $\$ B 0$ | 176 |
| 50 | $\$ 31$ | 49 | $\$ B 1$ | 177 |
| 51 | $\$ 32$ | 50 | $\$ B 2$ | 178 |
| 52 | $\$ 33$ | 51 | $\$ B 3$ | 179 |
| 53 | $\$ 34$ | 52 | $\$ B 4$ | 180 |
| 54 | $\$ 35$ | 53 | $\$ B 5$ | 181 |
| 55 | $\$ 36$ | 54 | $\$ B 6$ | 182 |
| 56 | $\$ 37$ | 55 | $\$ B 7$ | 183 |
| 57 | $\$ 38$ | 56 | $\$ B 8$ | 184 |
| 58 | $\$ 39$ | 57 | $\$ B 9$ | 185 |
| 59 | $\$ 3 A$ | 58 | $\$ B A$ | 186 |
| 60 | $\$ 3 B$ | 59 | $\$ B B$ | 187 |
| 61 | $\$ 3 C$ | 60 | $\$ B C$ | 188 |
| 62 | $\$ 3 D$ | 61 | $\$ B D$ | 189 |
| 63 | $\$ 3 E$ | 62 | $\$ B E$ | 190 |
| 64 | $\$ 3 F$ | 63 | $\$ B F$ | 191 |

Examples (central or channel-related):
Call up status of scene 5 :
$\rightarrow$ Send \$04 to the relevant scene object.
Save current status with scene 5 :
$\rightarrow$ Send $\$ 84$ to the relevant scene object.

### 9.2.3 Teaching in scenes without telegrams

Instead of defining scenes individually by telegram, this can be done in advance in the ETS. This merely requires the All channel scene statuses parameter (Scenes parameter page) to be set to Overwrite on download.

The required status can then be selected for each of the 8 possible scene numbers in a channel (= Status after download parameter).
After the download, the scenes are already programmed into the device.
Later changes via teach-in telegrams are possible if required and can be permitted or blocked via a parameter.

### 9.3 Conversion of percentages to hexadecimal and decimal values

| Percentage <br> value | $\mathbf{0 \%}$ | $\mathbf{1 0 \%}$ | $\mathbf{2 0 \%}$ | $\mathbf{3 0 \%}$ | $\mathbf{4 0 \%}$ | $\mathbf{5 0 \%}$ | $\mathbf{6 0 \%}$ | $\mathbf{7 0 \%}$ | $\mathbf{8 0 \%}$ | $\mathbf{9 0 \%}$ | $\mathbf{1 0 0 \%}$ |
| :--- | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| Hexadecimal | 00 | 1 A | 33 | 4 D | 66 | 80 | 99 | B3 | CC | E6 | FF |
| Decimal | 00 | 26 | 51 | 77 | 102 | 128 | 153 | 179 | 204 | 230 | 255 |

All values from 00 to FF hex. ( 0 to 255 dec .) are valid.


[^0]:    ${ }^{1}$ see parameter Use on parameter page General.

[^1]:    ${ }^{7}$ Upon double-click with object type $=$ height $\%+$ slat $\%$
    ${ }^{8}$ Upon double-click with object type $=$ height $\%+$ slat $\%$

[^2]:    ${ }^{9}$ or only
    ${ }^{10}$ Thus, the window status can be received either via the own inputs 11,12 , or from other bus sharing units (binary input, button interface, etc.).

[^3]:    ${ }^{11}$ Also in the case of direct control: button/switch at I1

[^4]:    ${ }^{17}$ For type of hanging $=$ Roller blinds / awning / general drive
    ${ }^{18}$ For type of hanging $=$ blinds

[^5]:    ${ }^{19}$ Parameter page Sun protection
    ${ }^{20}$ Window open or tilted
    21 Termination by closing the window or blocking.
    ${ }^{22}$ The parameter Position after end of ventilation is not taken into account.
    ${ }^{23}$ Parameter page Sun protection: Parameter Behaviour when heating support is not required any longer or Behaviour when cooling support is not required any longer.

[^6]:    24 Here, the parameter Response after return to automatic operation is not taken into account.
    25 The parameter Position after end of ventilation is not taken into account any longer.
    ${ }^{26}$ Parameter page Sun protection
    27 Window open or tilted
    28 Termination by closing the window or blocking.
    29 The parameter Position after end of ventilation is not taken into account.
    ${ }^{30}$ Parameter page Sun protection: Parameter Behaviour when heating support is not required any longer or Behaviour when cooling support is not required any longer.

[^7]:    ${ }^{35}$ Only JU 1
    ${ }^{36}$ In this case, the movement is finished by the drive itself, when reaching the end position
    37 JU 1 RF: Mains restoration

[^8]:    42 JU 1 RF: Mains restoration

[^9]:    ${ }^{43}$ Direct control of C1 possible.
    44 Direct control of C1 possible.

[^10]:    46 JU 1 RF: Mains restoration

[^11]:    47 JU 1 RF: Mains restoration

[^12]:    48 JU 1 RF: Mains restoration

[^13]:    ${ }^{49}$ Only available for 12
    ${ }^{50}$ Only available for 12

[^14]:    ${ }^{54}$ In this way, window contact inputs I 1 and I 2 can be used for C 1 , as well as for other bus sharing units, blind actuators (displays etc.).

[^15]:    ${ }^{56}$ Direct control: This parameter is only available at I1 and only for the blinds function.

[^16]:    ${ }^{57}$ Applies here to I1, and for I2 if used.
    ${ }^{58}$ Applies here to I1, and for 12 if used.
    ${ }^{59}$ Applies here to I1, and for 12 if used.

[^17]:    ${ }^{60}$ Direct control: This parameter is only available for the switch or button function.

[^18]:    ${ }^{63}$ Normal KNX operation, without direct control.

[^19]:    65 The desired position is set on the Presets parameter page.
    ${ }^{66}$ Actual switching status of the window contact
    ${ }^{67}$ Telegram which is sent from an external input.
    ${ }^{68}$ Actual switching status of the window contact
    ${ }^{69}$ Telegram which is sent from an external input.

[^20]:    ${ }^{74}$ Direct control is also possible with a switch, depending on the application.

[^21]:    75 The remaining parameters on the Configuration options page are only relevant in conjunction with communication objects and are not considered in any more detail here.
    ${ }^{76}$ Included here as an example. All other functions can also be used.
    ${ }^{77}$ Direct control is also possible with a switch, depending on the application.

[^22]:    ${ }^{78}$ Normal KNX operation, without direct control.

